

Superior Clamping and Gripping



SCHUNK Gripping Systems

Product Overview

Superior Clamping and Gripping



Henrik A. Schunk, Kristina I. Schunk, brand ambassador Jens Lehmann, and Heinz-Dieter Schunk

Top Performance in the Team

SCHUNK is the world's No. 1 in clamping technology and gripping systems – from the smallest parallel gripper to the largest standard chuck jaw program.

As a competence leader, we recognize and develop standards with a large potential for the future, which will drive the rapid progress in many industries.

Our customers profit from the expert knowledge, the experience and team spirit of almost 3,000 employees in our innovative family-owned company.

The Schunk family wishes you improved end results with our quality products.

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Superior Clamping and Gripping

Jens Lehmann stands for safe, precise gripping and holding. As a brand ambassador of the SCHUNK team, the No. 1 goalkeeper represents our global competence leadership for gripping systems and clamping technology. The top performance of SCHUNK and Jens

Lehmann are characterized by dynamics, precision, and reliability.

For more information visit our website: schunk.com/lehmann



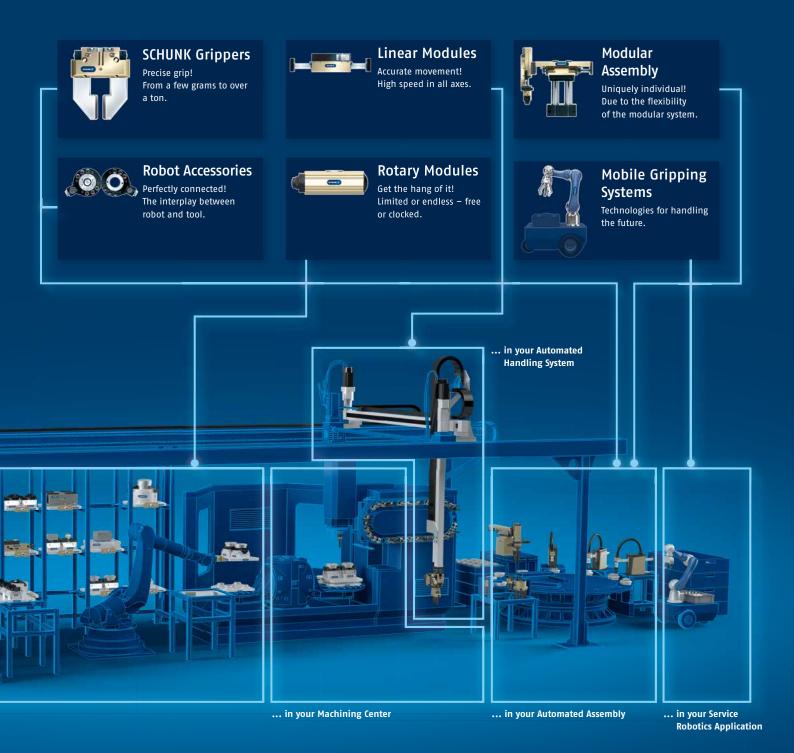






It's time to use of your machine's full potential!

With our superior components, find potentials in your machine, where you would least expect to find them. SCHUNK SYNERGY – the perfectly harmonized interplay between gripping systems and clamping technology – turns our customers into productivity champions.



Benefit from the SCHUNK Modular System with over 4,000 Standard Components.

For every Robot, for every Industry, for every Handling Task.

SCHUNK sets standards in the automotive industry worldwide with its components and gripping systems.

Our robot accessories include a uniquely comprehensive standard range of modules for the mechanical, sensory, and power connection of handling devices and robots. The comprehensive range of robust and long-lasting grippers for small components and universal grippers features high product quality, precision, and numerous monitoring options. What's more, SCHUNK's axis system handling solutions open up new perspectives for cost and benefit-optimized automation solutions from a single source.



system HWS

change system SWS

SCHUNK Gripping Systems

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Robots: Equipped by SCHUNK

The SCHUNK End-of-Arm Competence for your Robot. From the standard Component to the standard Gripping System.

SCHUNK provides the most comprehensive range of modules for the mechanical, sensory, and power connection of handling devices and robots. Quick-change systems, rotary feed-throughs, collision and overload protection modules, force sensors, as well as compensation units, and insertion units ensure optimum interplay between the robot arm and gripper. The basis for this cutting-edge technology "Made in Germany" is our constant innovation.



SCHUNK Gripping Systems



Feeding through

Over 50 process-stable pneumatic, electrical or combined SCHUNK rotary feed-throughs.

schunk.com/feeding-through





DDF 2

Monitoring

Over 60 collision and overload sensors used to monitor, record and avoid collisions.

schunk.com/monitoring





Measuring

Over 150 sensors for precise measurement of forces and moments.

schunk.com/measuring



Changing

More than 100 precise quick-change systems for flexible, fast change of effectors.

schunk.com/changing



EWS

Compensating

Over **90** components to compensate position deviations and tolerances between the robot and the tool.

schunk.com/compensating







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AGE-W

TCU

Page 18

SCHUNK Grippers

The world's most extensive gripper portfolio with over 2,550 pneumatic and electric components. schunk.com/grippers







DPG-plus



PHL





PGN-plus-P

Machining

Flexible SCHUNK deburing spindles for the use on robots with up to 65,000 revolutions per minute.

schunk.com/machining



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Further production information is available at: schunk.com/robot-accessories

by

SCHUNK

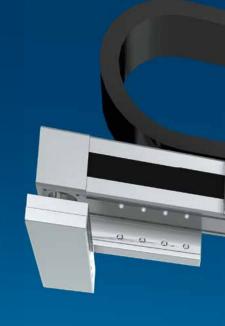
Gantry Systems: Equipped by SCHUNK

SCHUNK End-of-Arm Competence for your Gantry. Over 4,000 Components for Handling and Assembly.

The linear module product offering combined with rotary modules, swivel units, grippers, quick-change systems, rotary indexing tables and sensor systems, SCHUNK opens up new perspectives for cost and useoptimized automation solutions.

Designed to be compact and from the modular system: From the axis right up to the gripper finger and combined for customized axis system handling solution.





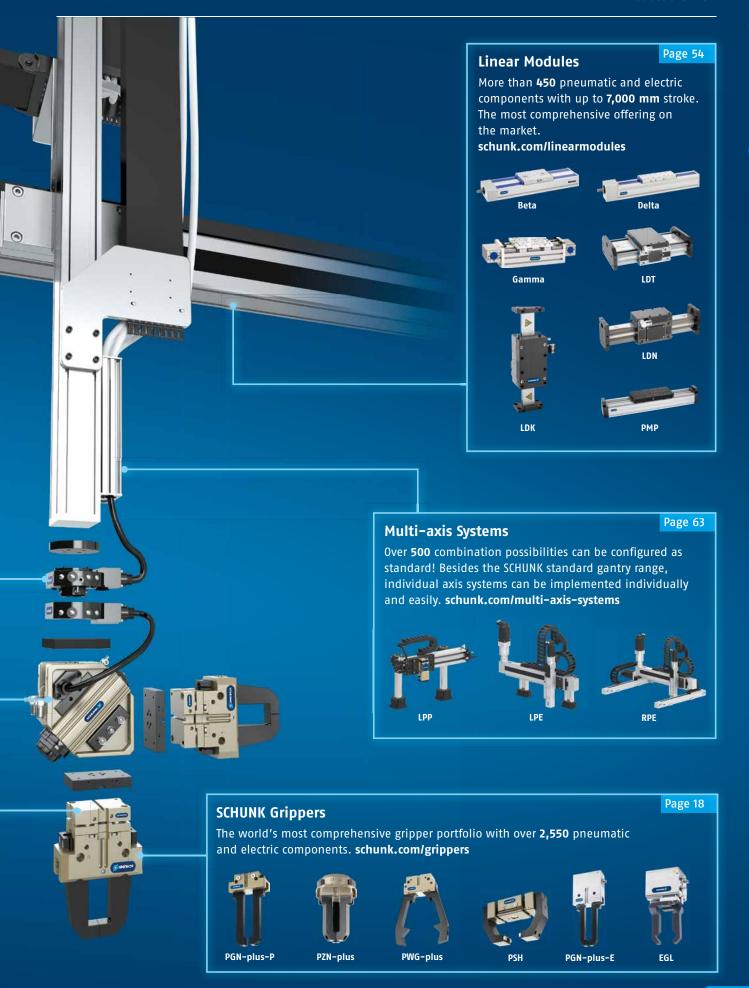






SCHUNK Gripping Systems

Product Overview



Assembly Automation: Equipped by SCHUNK

100% Flexibility with the Modular System.

Design an infinite number of applications for small parts handling and assembly automation with the SCHUNK modular assembly system. An incredible variety of automation solutions can be realized with standard modules from the SCHUNK modular system.

















Cobots Equipped by SCHUNK

Gripper Gripper

The Mega Trend of Human/Robot Collaboration

From robots that replace workers to robots that serve as helpful colleagues, the field of robotic automation is experiencing a new trend that represents a huge challenge for component manufacturers.

Whenever full automation of production or assembly lines is not the most economically feasible option, it is necessary to single out individual processes to be delegated between humans and robots. In such situations, autonomous cobots, meaning robots used in the worker's immediate environment, can handle nonergonomic or monotonous tasks such as assisting with lifting or positioning loads. This reduces the physical workload for workers and makes the process more

efficient. At the same time, humans and robots working hand in hand helps to minimize space requirements and to increase flexibility.

The number of robotic assistance systems will increase in the future, especially with regard to assembly applications. Reliable grippers, safety functions, sensor systems, and a universal networking at the component level will be vital.

As the competence leader for gripping systems and clamping technology, SCHUNK is intensely committed to this new challenge.



The NEW SCHUNK Grippers for Collaborative Operations





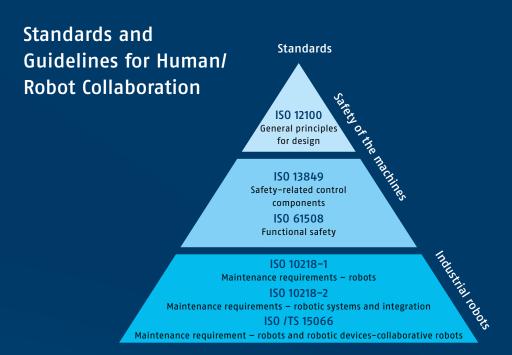












From standard requirements to customer solutions

The listed standards and guidelines are not exhaustive. For every application the applicability of further standards or guidelines have to be determined.









The Path toward the optimum Gripper for your HRC Application

To determine the optimum gripper for collaborative applications, the properties of the task, workpiece, and gripper must be taken into account.

The **SCHUNK Co-act team** recommends a structured approach, considering all factors and parameters.



Step 1

Task description and feasibility check

 Are the task and workpiece suitable for human/robot collaboration?



Step 2

Selection of the robot or cobot

- Definition of the basic system with mechanical and electrical connection of the peripheral devices
- Ensuring a defined control



Step 3

Selecting the gripper in collaboration with the SCHUNK Co-act team considering the following points:

- Workpiece with respect to gripping position, required gripping force, and required stroke
- Pick and place position and in turn analysis of the interfering contour
- Connection to the superordinate mechanical and electrical periphery
- Clamping and shearing points on the gripper or the attached fingers

Assembly Automation: Equipped by SCHUNK

The new Standard in Assembly Automation. The 24 V Mechatronics Offering from SCHUNK.

For the first time, complete assembly systems with linear modules, rotary modules and grippers can be entirely implemented using the 24 V technology as a basis. The reduced maintenance costs, high process stability, and lower operating costs are revolutionary.

The 24 V mechatronics range offers the advantages of mechatronic modules while being as simple as pneumatics. This results in revolutionary advantages for handling in assembly automation, for instance such as a very low maintenance effort, simple and fast commissioning, and high energy efficiency.

Pick & Place Production Cell

Electric, simple, compact and fast implementation.



Easy to Start Up!

Simple commissioning of the mechatronic modules. Simpler and more intuitive than pneumatic modules



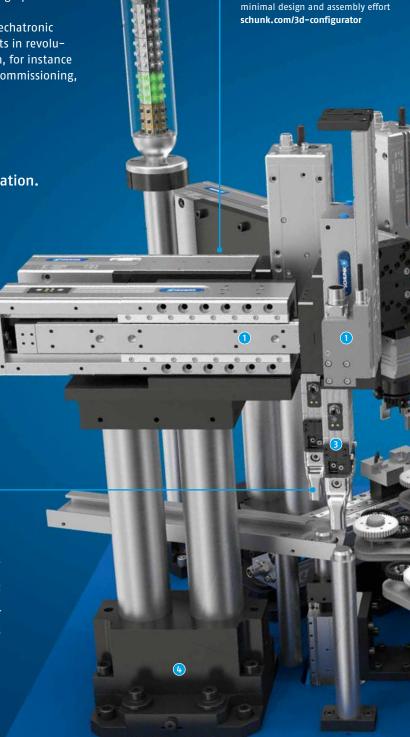
Plug & Work!

Easily combine, integrate and seamlessly commission mechatronic SCHUNK grippers, rotary and linear modules from the modular system

- 1 Electric Linear Module ELP
- Page 57
- **2** Electric Rotary Gripping Unit EGS
- Page 52
- 3 Electric Gripper for Small Components EGP
- Page 34
- SCHUNK Pillar Assembly System SAS
- Page 78

Further information on the new standard in assembly automation:

schunk.com/standard-in-assembly-automation



Easy to Create!

Complete Pick & Place applications

can be intuitively configured with







Easy to Integrate!

Versatile and energy-efficient integration into the system. Consistent supply concept with standardized connecting plug and control with digital I/O. Using conventional, standardized cables and distributors, systems can be implemented easily and very compactly





Easy to Use!

Low-wear and maintenance-free modules for smooth operation of handling and assembly systems without machine shutdown.

Simple setting options can be used to react quickly to process changes, right up to automatically adjusting the modules







4

Easy to Save Money!

Observing the procurement, operating and maintenance costs comparing with purely pneumatic systems, the deployment becomes economically after just a few million cycles.

MECHATRONIK³ Alternative – Adaptable – Intelligent

One Strategy - 3 Features

Mechatronics³ is the strategy with which SCHUNK is the first manufacturer to bundle a comprehensive mechatronic product portfolio. Its three features – Alternative, Adaptable and Intelligent – combine to form a unique modular system. This combines our decades of experience in the field of pneumatics and our pioneering success in the field of mechatronics, and offers sophisticated and efficient automation solutions for almost any mechatronic requirement.

With mechatronic SCHUNK products, the changeover to electrically driven components is as simple and easy as it is feasible. From simple pneumatic alternatives right up to highly intelligent modules, SCHUNK provides the right product for any application.



Benefit from the leading Modular System with the 3 Features into which all mechatronic SCHUNK Products can be classified:

Alternative

Replace pneumatics 1:1 while maintaining the same performance.

Common pneumatic functions can be replicated with 100% accuracy using SCHUNK mechatronic components.

Adaptable

Driven by conventional servomotors.

A motor adapter allows you to connect conventional servomotors to your SCHUNK components.

Intelligent

Fully integrated motor and control technology.

The controller is either integrated into the SCHUNK component to save space, or installed in the control cabinet.

SCHUNK Components

offer maximum Flexibility when it comes to Incorporating them into existing Control System Concepts

Standard mechatronic SCHUNK components offer the greatest flexibility when it comes to connecting customized control concepts. Depending on your requirements, you have the choice between various SCHUNK modules with integrated or external drive, and drive regulators and the possibility to control via digital I/O signals.

From the customer controller right up to components, SCHUNK offers the appropriate components and therefore maximized flexibility for every control concept.

Customer Controller

The controller serves as the interface with the application and is specified by the customer. SIEMENS® | BoschRexroth® | BECKHOFF® | B & R® | Schneider Electric® | Lenze | More upon request

PROFINET/PROFIBUS/CAN/DeviceNet More on request Digital IO Link Drive controller I/O distributor Master e.g. SCHUNK/Siemens®/BoschRexroth® Others on request Standard servomotors IO-Link Digital e.g. SCHUNK/ 1/0 SIEMENS®/

SCHUNK products mechatronics alternative to pneumatics



SCHUNK

Products



BoschRexroth®





Alternative

Communication-interfaces & periphery

SCHUNK Products

Digital I/O

Replace pneumatics 1:1 while maintaining the same performance.

Adaptable
Driven by
conventional motors.

Intelligent Controller external, motor integrated Intelligent Motor and controller fully integrated









SCHUNK Grippers The world's most proven Grippers on the Market.

SCHUNK offers the world's most comprehensive portfolio of grippers. Standard grippers, ready-to-install gripping system assembly groups and an extremely wide range of customized gripping system solutions for your handling and assembly, automation and robot end-of-arm solution. We always meet the most complicated gripping requirements, and we solve them. The result: robust and durable gripping systems which ensure maximum reliability in systems and machines all over the world for 30 years.





Over **2,500** standard grippers
Over **300** mechatronic grippers

More than 12,000 implemented gripping system solutions

More than 1,000,000 products in use worldwide



















The new SCHUNK Universal Grippers

PGN-plus-P and PGN-plus-E

In a Class of its Own!



SCHUNK Grippers

Product Overview

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The new SCHUNK Gripper PGN-plus-P

The world's most proven gripper on the market – Now NEW with permanent lubrication in the multi-tooth guidance. Lifelong maintenance free.* Guaranteed!

With the new SCHUNK gripper PGN-plus-P, SCHUNK is raising the bar even further for pneumatically actuated universal grippers. By consistently optimizing the multi-tooth guidance, it is setting a new benchmark for the market. At the same time the PGN-plus-P benefits from the unique SCHUNK accessory program for the nearly complete spectrum of feasible automation applications.

Your benefits:

- NEW: Up to 50% longer gripper fingers due to higher maximum moments
- NEW: Up to 50% higher gripping force due to the increased surface of the drive piston
- NEW: Lifelong maintenance-free * due to the perfected SCHUNK multi-tooth guidance with consistent lubrication pockets
- NEW: Maximum process reliability with up to 60% larger diagonal pull area and therefore lower surface pressure
- Diversity with the accessories
 wide range of high-quality accessory components and corresponding sensor systems.



* Under normal, clean operating conditions

schunk.com/pgn-plus-p



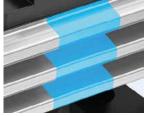
Up to 50% longer gripper fingers – due to higher maximum moments

The improved multi-tooth guidance enables the use of even longer gripper fingers for the same gripper size due to higher maximum moments, without overloading the guidance. Interfering contour-optimized gripping with confined handling tasks therefore become even easier.



Up to 50% higher gripping force

The larger surface of the drive piston in the available, and at the same time compact assembly space increases the gripping force with the PGN-plus-P. In relation to the gripper size, higher work-piece weights can be handled.



Maximum service life due to the perfected SCHUNK multi-tooth guidance with consistent lubrication pockets

Permanent lubrication pockets ensure a continuous grease supply. At the same time, it ensures that an even lubricant film is created rapidly, even with short strokes.



Maximum process reliability with up to 60% larger diagonal pull area

A larger diagonal pull surface and therefore lower surface pressure, for process reliability and low-wear transmission of power to the base jaw.

	2-Finger Parallel Gripper		
	MPG-plus	MPG	ктс
		COUNTY	
Technical data			
Number of sizes	7	9	1
Gripping force [N]	29 370	7 – 270	13
Stroke per jaw [mm]	1.5 - 10	1 14	4.5
Weight [kg]	0.022 - 0.63	0.01 1.35	0.08
Recommended workpiece weight [kg]	0 1.25	0 1.9	0.07
Closing/opening time [s]	0.011 0.08/0.011 0.08	0.01 0.085/0.01 0.085	0.05/0.05
Max. permissible finger length [mm]	80	80	50
Repeat accuracy [mm]	0.02	0.02	0.02
Protection class IP	30	30	20
Cleanroom class ISO 14644-1	5	5	
Sensor systems	++	++	+
Wide variety	++	++	+
Description	The most powerful pneu- matic miniature parallel gripper on the market with a unique combina- tion of oval piston drive and cross roller guide	2-finger parallel gripper with smooth roller guides of the base jaws	2-finger parallel gripper with center bore
Field of application			
	 Gripping and moving For small to mediumsized workpieces In the field of assembly, testing, laboratory, pharmacies 	 Gripping and moving For small to medium- sized workpieces In the filed of assem- bly, testing, laboratory, pharmacies 	 Gripping and moving For small to medium- sized workpieces Equipped with a con- tinuous center bore for workpiece supply, sensor or actuator systems
Ambient conditions			
Clean	•	•	•
Contaminated/coarse dust	0	0	0
Contaminated/fine dust and liquids			
Contaminated/aggressive liquids			
High temperature range > 90° C			•
Cleanroom	0	0	0

^{• =} very highly suitable • highly suitable • suitable in customized version + = medium-sized selection + + = wide selection +++ = very wide selection

KGG	RH	PGN-plus-P	PGN-plus	JGP
	COLUNI D			
7	10	5	11	10
45 540	13 460	220 4200	123 21150	123 7400
10 60	2.5 40	213	2 45	235
0.09 4.2	0.04 1.1	0.17 1.9	0.08 39.5	0.08 17.5
0 2.7	02.3	015	080.5	030
0.03 0.29/0.03 0.25		0.02 0.12/0.02 0.12		0.02 0.7/0.02 0.7
160	100	200	400	300
up to 0.02	up to 0.01	0.01	up to 0.01	up to 0.01
40	30	40	40/64	40
			5	
+	+	+++	+++	++
++	+	+++	+++	+
Narrow 2-finger parallel gripper with large stroke	The RH series is an attractively priced gripping system, which is particularly suitable for light applications	Universal 2-finger parallel gripper with a high gripping force and high maximum moments due to the multi-tooth guidance	Universal 2-finger parallel gripper with a high gripping force and high maximum moments due to the multi-tooth guidance	Universal 2-finger paral- lel gripper of the compact class with T-slot guidance and good cost- performance ratio
 Universal use For light to medium- sized workpiece weights With a large range of stroke 	With low process forces	 Optimum standard solution for many fields of application Universal use 	 Optimum standard solution for many fields of application Universal use 	 Optimum standard solution for many fields of application Universal use In the areas of machine and plant construction, assembly and handling as well as the automotive industry
•	•	•	•	•
0		•	•	•
		0	0	
•		•	0	
0		•	•	
9		•	•	

PGF	PGB	DPG-plus	PHL
-		4.4	_
5	4	11	5
240 1900	90 610	110 11250	390 4630
7.5 31.5	410	2 45	30 160
0.3 5.3	0.28 1.32	0.12 52	1.38 24.18
07.1	03.3	0 46.35	0 15.5
0.03 0.4/0.03 0.4	0.02 0.08/0.02 0.08	0.03 1.1/0.03 1.1	0.12 1.82/0.12 2.91
125	125	380	800
up to 0.02	0.01	up to 0.01	0.02
40	40	67	41
		5	
+	++	+	++
+	+	+	++
Universal parallel gripper with surface-guided base jaws	Universal 2-finger parallel grip- per with a high gripping force and high moment capacity due to the multi-tooth guideway as well as the center bore	Despite the high moment load of the base jaws, this sealed 2-finger parallel gripper meets the IP67 requirements and does not permit any substances from the working environment to penetrate the interior of the unit	2-finger parallel gripper with long jaw stroke for large parts and/or a broad range of parts
For high part diversities due to its long jaw stroke and high gripping forces	Universal use Suitable for applications that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recognition systems	 Ideally suitable for handling of rough or dirty workpieces Its field of application extends from the loading and unloading of machines, such as in the case of sanitary blocks, grinding machines, lathes or milling machines, to handling tasks in painting plants, in powder- processing or underwater 	 Optimum standard solution for many fields of application Universal use In the areas of machine and plant design, assembly and handling as well as the automotive industry
			_
•	•	•	•
0	•	•	0
		•	0
		•	
0	0	•	
J	J	•	

PFH-mini	PFH	PSH	SPG
_			
3	4	4	1
630 2950	2200	320 1760	10000
30 100	150 300	14100	100
2.65 12.6	18.9 33.6	0.77 8.05	35
013	014.7	0 8.8	50
0.3 1.0/0.3 1.2	0.7 1.25/0.7 1.25	0.12 04/0.12 0.4	1.5/1.5
250	900	300	500
0.05	0.02	up to 0.05	0.1
41	30	67	30
++	++	+	+
++	+	+	+
Gripper with long jaw stroke for large parts and a broad range of parts	2-finger parallel gripper with long jaw stroke for large parts and/or a broad range of parts	2-finger parallel gripper with long jaw stroke and dirt-resis- tant round guides	Sturdy 2-finger parallel gripper for heavy components and a broad part range, equipped with robust guides and therefore it is suitable for high gripping forces and maximum moment loads.
For precise handling of a wide variety of workpieces	Particularly suitable for han- dling vehicle wheel rims	• For a wide range of parts	 Covering a wide range of parts with a long jaw stroke High gripping force for high workpiece weights
•	•	•	•
0	0	•	0
0	0	•	
		•	
•	•	•	
		0	

2-Finger Parallel Gripper

Pneumatic

SCHUNK Gripper MPG-plus

The most powerful pneumatic miniature parallel gripper on the market.

Highly efficient small parts handling in the most compact space. With its power density, the MPG-plus sets the new standard for handling small parts. The unique combination of oval piston and cross roller guide of the MPG-plus ensures higher efficiency because of higher force and load capacity.

Your benefits:

- 25% higher gripping forces with identical size
- 25% longer gripper fingers with identical gripper size
- 30% higher basic load rating by improved guidance (cross roller guide)
- 10% less weight for higher dynamics
- 20% improved closing time for shorter cycle times

comparison with the SCHUNK MPG gripper, which until now defined the benchmark in small parts handling.





MPG-plus: award-winning at the AUTOMATICA show

schunk.com/mpg-plus



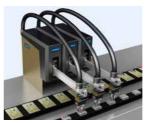
Larger piston surface – more precise guidance

The larger oval piston surface and increase in the number of cross rollers ensure significantly improved efficiency. The improved cross roller guide with an increased number of junction rollers permits higher gripping forces.



Variable mounting options – maximum flexibility

Diverse mounting options ensure quick, easy gripper assembly and exchange. The gripper can be easily positioned using the centering sleeves and can be screwed through and fixed either laterally or at the bottom.



From a single source – Pick & Place with MPG-plus

Combine the MPG-plus miniature parallel gripper with the PPU-P from SCHUNK, the fastest pneumatic pick & place unit on the market. Benefit from highspeed pick & place with 95 cycles per minute.



Add-on valve ABV – shorter hosing, improved cycle time

The electrically controlled 3/2 pneumatic micro valves ABV are screwed onto the gripper. This hose-free direct assembly minimizes the hosing effort and reduces cycle times.

	3-Finger Centric Gripper		
	MPZ	PZN-plus	
Technical data			
Number of sizes	6	11	
Gripping force [N]	20 310	255 57300	
Stroke per jaw [mm]	1 - 5	2 45	
Weight [kg]	0.01 0.29	0.13 80	
Recommended workpiece weight [kg]	0 1.15	0 227	
Closing/opening time [s]	0.02 0.06/0.02 0.06	0.02 4.6/0.02 3	
Max. permissible finger length [mm]	45	250	
Repeat accuracy [mm]	0.01	up to 0.01	
Protection class IP	40	40/64	
Cleanroom class ISO 14644-1	5	5	
Comprehensive ranges	+	+++	
Variety of sensor systems	+	+++	
Description	Small 3-finger centric gripper with base jaws guided on T-slots	Universal centric gripper with high gripping force and maximum moments due to multi-tooth guidance	
Field of application			
	 Universal use Particularly suitable for gripping small workpieces 	Universal use due to numerous product variants; also in areas where there are special demands on the gripper (temperature, chemical durability, con- tamination, and much more)	
Ambient conditions			
Clean	•	•	
		_	
Contaminated/coarse dust	0	•	
Contaminated/coarse dust Contaminated/fine dust and liquids	0	•	
	0	•	
Contaminated/fine dust and liquids	0		

JGZ	PZH-plus	PZB-plus	DPZ-plus
7	4	9	8
225 7990	375 4200	340 27400	230 16500
2 16	20 75	2 35	2 25
0.12 8	1.5 33	0.26 53	0.2 20.1
030	0 22	0100	060
0.02 0.8/0.02 0.8	0.25 1.05/0.2 0.85	0.02 2.5/0.02 2.5	0.03 1.8/0.03 1.8
200	400	250	160
up to 0.01	up to 0.02	up to 0.01	up to 0.01
40	40	40	67
5	5		5
+	+	+	+
++	+	++	+
Universal 3-finger centric gripper of the compact class with T-slot guidance and best cost-performance ratio	Universal centric gripper with high gripping force and maximum moments due to multi-tooth guidance	Universal 3-finger centric gripper with large gripping force and high maximum moments per finger, plus center bore	Despite the high moment load of the base jaws, this sealed 3-finger centric gripper meets the requirements of IP67 and does not permit any substances from the working environment to penetrate the interior of the component
Optimum standard solution for many fields of application Universal use In the areas of machine and plant design, assembly and handling as well as the automotive industry	 Universal use due to numerous product variants; also in areas where there are special demands on the gripper (temperature, chemical durability, contamina- tion, and much more) 	 Universal use Suitable for fields of application that require a center bore, e.g. for workpiece feeding, special sensor systems or optical recog- nition systems 	 Ideally suitable for handling of rough or dirty workpieces Its field of application extends from the loading and unload- ing of machines, such as in the case of sanitary blocks, grinding machines, lathes or milling machines, to handling tasks in painting plants, in powder- processing or underwater
•	•	•	•
•	0	0	•
	0	0	•
	0	0	0
	0	•	
			0

		Multi-finger Centric Gripper
PZH-SF-mini	PZH-SF	PZV
1	1	5
		570 6900
		4 16
3.3	20	0.5 10
0 9.8	08	034.5
0.5/0.5	0.5/0.5	0.02 0.15/0.02 0.15
80	140	140
0.05		up to 0.01
64	40	40
+	+	+
+	+	+++
Universal 3-finger centric gripper with a large, rotating jaw stroke capable of handling a broad range of workpiece sizes and a round guidance which is protected against dirt	Universal 3-finger centric gripper with a large, rotary jaw stroke capable of handling a broad range of workpiece sizes and a round guidance which is protected against dirt	The multi-finger gripper for applications in which two or three fingers are insufficient
 Long stroke for a large range of parts or for undercut sections Optimum for rotationally symmetric parts 	Particularly suitable for handling vehicle wheel rims	 4-finger centric grippers have advantages over the usual 3-finger centric grippers, for example when cylindrical workpieces are being magazined in tablets The PZV process-reliably handles the workpieces despite the interfering contours
•	•	•
0	0	•
•	•	
		•

The new SCHUNK 3-Finger Centric Gripper PZN-plus-P

Now NEW with permanent lubrication in the multi-tooth guidance. Lifelong maintenance-free.*

The new SCHUNK PZN-plus-P gripper is now equipped with a permanent lubrication in the multi-tooth guidance which, under normal, clean operating conditions, guarantees lifelong maintenance-free operation. With short strokes in particular, the continuous lubrication pockets produce a particularly fast and even distribution of lubricant along the entire multi-tooth guidance contour. Compared with conventional T-slot-guided 3-finger centric grippers, the new SCHUNK PZN-plus enables up to 50% longer gripper fingers and a finger load up to 120% higher.

Your benefits:

- NEW: Up to 50% longer gripper fingers due to higher maximum moments
- NEW: Up to 50% higher gripping force due to the increased surface of the drive piston
- NEW: Lifelong maintenance-free* due to the perfected SCHUNK multi-tooth guidance with consistent lubrication pockets
- Up to 120% higher finger load
 The improved multi-tooth guidance facilities higher maximum moments due to the enlarged guiding areas.
- Rapid and even lubricant distribution even with short strokes
- Continuously reliable and robust



schunk.com/pzn-plus-p

* Under normal, clean operating conditions

SCHUNK Miniature Gripper MPZ

SCHUNK

schunk.com/mpz

Powerful handling of small parts

The powerful 3-finger miniature centric gripper can be used in small parts handling systems, e.g. for handling and mounting products such as needles, microprocessors or small electric components. A characteristic feature of the MPZ is the tried-and-tested, accurate T-slot guidance with hardened, ground steel base jaws. This ensures reliability and high performance. The gripping force maintenance device that can be integrated as an option is protected by very small springs during opening and closing. For example, this prevents loss of components in the event of a sudden drop of the pneumatic pressure.

Your benefits:

- · Proven T-slot guidance
- Wedge-hook principle for high force transmission and synchronized gripping
- · Gripping force maintenance device optional

	2-Finger Angular Grippe	er		2-Finger Radial Gripper
	SGB	swg	PWG-plus	PRG
Technical data				
Number of sizes	3	8	8	8
Gripping moment [Nm]	0.9 4.95	0.01 - 2.8	3.32 1025	2 295
Opening angle per jaw [°]	8	15	15	3090
Weight [kg]	0.04 0.06	0.0025 - 0.213	0.13 13.6	0.13 6.72
Recommended workpiece weight [kg]	00.8	00.46	023.13	0 6.96
Closing/	0.06 0.08/	0.015 0.03/	0.06 0.32/	0.06 0.75/
opening time [s] Max. permissible finger length	0.04 0.05 50	0.02 0.06 42	0.01 0.46 300	0.06 0.92 240
[mm]				
Repeat accuracy [mm]	0.1	0.05	0.02	up to 0.05
Protection class IP	20	30	30	20
Cleanroom class ISO 14644-1				
Sensor systems	+	+	++	++
Comprehensive ranges	+	+	++	++
Description	Small, simple actuated plastic angular gripper with spring reset	Narrow double-act- ing 2-finger angular gripper	Robust 2-finger angu- lar gripper with oval piston and bone drive	180° radial gripper with powerful 1-shift slotted link gear and oval piston
Field of application				
	Universal use With special requirements on corrosion resistance and antistatic properties of the gripping unit	 Universal use Suitable for applications which require a stacked, spaceoptimized gripper arrangement 	· Universal use	 For areas of application which, in addition to a large gripping force, require the shortest possible motion sequences through the radial design of the jaw stroke
Ambient conditions				
Clean	•	•	•	•
Contaminated/coarse dust	0	0	0	0
Contaminated/fine dust and liquids			0	
Contaminated/aggressive liquids			0	
High temperature range > 90 °C		•	•	•
Cleanroom	0	0	0	0

^{• =} very highly suitable • = highly suitable • = suitable in customized version * The GAP Is an angular parallel gripper, which means the values must be understood as forces [N].

^{+ =} medium-sized selection +++ = wide selection +++ = very wide selection

DRG	GAP	3-Finger Angular Gripper SGW
		Innae 8
5	3	3
8.2 143	92 430*	1.35 7.45
10 90	30 90	8
0.5 4.46	0.3 1.33	0.05 0.17
0 7.2	0 125	013
0.4 0.3 <i>l</i> 0.5 0.6	0.09 0.35/ 0.09 0.35	0.02 0.02/ 0.03 0.03
125	65	50
0.1	0.05	0.1
67	40	20
++	+	+
++	++	+
Sealed 180° angular gripper for use in dirty environments	2-finger angular paral- lel gripper with gripper finger actuation of up to 90 degrees per jaw	Small, simple actuated plastic angular gripper with spring return
 For applications requiring a large opening range Particularly suitable for the use in dirty environments 	 Gripping and moving For small to medium-sized workpieces 	Universal use With special requirements on corrosion resistance and antistatic properties of the gripping unit
•	•	•
•	0	0
•		
•		
•		

SCHUNK Gripper PWG-plus

Compact powerhouse

The double oval piston drive, the one-piece, high-strength aluminum housing and the practically wear-free bone drive make the PWG-plus 2-finger angular gripper a compact and robust powerhouse. Depending on the application it can be equipped with or without a mechanical gripping force maintenance device.

In addition, extensive accessories are available, including inductive sensors and magnetic switches.



schunk.com/pwg

Your benefits:

- Workpiece weights between 0.5 kg and 7.3 kg
- Gripping moments amount between
 3.5 Nm and 143 Nm
- Stroke per finger 15°
- Overgrip angle per jaw at least 3°
- Maximum force transmission and low wear due to robust bone drive
- High power density due to oval piston drive
- Flexible design of workpiece supports because of connection threads and centering possibilities

SCHUNK Grippers

Electric

	2-Finger Parallel Gripper			
	Alternative		Adaptable	
	EGP	PGN-plus-E	LEG	EGA
Technical Data				
Number of sizes	4	1	3	2
Gripping force [N]	12 300	110 - 570	300 1050	150 1300
Stroke per jaw [mm]	310	8	101 281	30 100
Weight [kg]	0.11 0.8	1.01	5.4 7.9	2.2 9
Recommended workpiece weight [kg]	0125	0 2.85	0 7.5	0 6.5
Closing/opening time [s]	0.03 0.49	0.26		
Max. permissible finger length [mm]	80	125	600	500
Repeat accuracy [mm]	0.02	0.01	0.05	0.05
Nominal voltage [V]	24 DC	24 DC	Motor-dependent	Motor-dependent
Nominal current [A]	0.14 0.3	0.6	Motor-dependent	Motor-dependent
Protection class IP	30	40	20	40
Type of measuring system			Motor-dependent	Motor-dependent
Great variety	++	+	++	++
Description	Electric 2-finger parallel gripper with smooth-run- ning roller bearing guide in the base jaw	Electric 2-finger parallel gripper with integrated motor and electronics as well as reliable multi-tooth guidance	Light long-stroke gripper for flexible and high- ly dynamic handling of different components	Electric 2-finger parallel gripper with adaptable servomotor
Motor & Controller				
Motor	Integrated	Integrated	Adaptable	Adaptable
Controller	Integrated	Integrated	External	External
	integrated	integrated		
Controller type			Motor-dependent	Motor-dependent
Field of application				
	 Gripping and moving For small to medium-sized workpieces with flexible force and high speed In the areas of assembly, testing, laboratory, pharmacies 	 Optimum standard solution for many fields of application Universal use 	 For very flexible gripping of various geometries and types of components Due to the servo-electric drives, the gripping posi- tion and the gripping force can be exactly determined 	 Gripping and moving For medium-sized work-pieces with flexible force and high speed
Ambient conditions				
Clean	•	•	•	•
Contaminated/coarse dust	0	0	0	•
Contaminated/fine dust and liquids		0		0
Contaminated/aggressive liquids				
High temperature range > 90 °C				
Cleanroom	0			

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Intel		

Intelligent						
MEG	PG	EGL	WSG	PEH		
3	1	1	3	3		
35 140	30 200	50600	580	150 1800		
610	34	42.5	32 105	60 100		
0.47 1.42	1.4	1.8	0.32 1.6	5.4 16.8		
00.7	1	0 - 3	00.4	09		
0.3 0.62	01	0.7	0.5 1.0	11.5		
64	140	165	170	270		
0.02	0.05	0.05	±0.03	±0.05		
24 DC	24 DC	24 DC	24 DC	24 DC		
0.6 1.3	1.4	2.5	0.3 0.9	2.4 10		
30	20	46	40	41		
	Incremental	Incremental	Incremental	Incremental		
+	+	+	++	+		
Electric 2-finger parallel gripper with smooth-running roller bearing guide in the base jaw	Servo-electric 2-finger par- allel gripper with sensitive gripping force control and long stroke	Servo-electric 2-finger parallel gripper with sensitive gripping force control and long stroke	Servo-electric 2-finger parallel gripper with sensitive gripping force control and long stroke	Servo-electric 2-finger parallel gripper with large jaw stroke for large parts and/or diverse parts spectrum		
Integrated	Integrated	Integrated	Integrated	Integrated		
External	Integrated	Integrated	Integrated	Integrated		
MEG-C						
 Gripping and moving For small to medium-sized workpieces with flexible force, stroke or speed 	 Universally applicable, highly flexible gripper For a wide range of parts and sensitive components 	 Various workpieces can be gripped either sensitively or with a high force Flexible workpiece handling possible even in a contami- nated environment 	 Universally applicable, highly flexible gripper For a wide range of parts and sensitive components 	Universally applicable, highly flexible gripper With a wide variety of parts		
•	•	•	•	•		
0		•		0		
0	0		0			
3	J		J			

	3-Finger Centric Gripper	Electromagnetic Grippers		
		Alternative		
EGN	EZN	EGM-M	EGM-B	
		COLARS		
3	2	6	8	
170 1000	140 800	780 11700	1800 20370	
816	610	1 7	F F 2F	
0.84 3.4	0.98 2.3	17	5.5 25	
0 - 5	0 4	075	0 118	
0.35 0.5	0.25 0.4	0.3	0.3	
200	125			
±0.01	±0.01			
24 DC	24 DC	400 AC	400 AC	
1 2.6	23	2.2 3.7	2.9 12.3	
41	41	54	54	
Resolver	Resolver			
++	++	+++	+++	
Servo-electric 2-finger parallel gripper with high gripping force and moment loads due to the multi-tooth guidance	Servo-electric 3-finger centric gripper with high gripping force and high maximum moment due to the multi-tooth guidance	Electric permanent magnetic grip- per for energy-efficient handling of ferromagnetic workpieces	Electric permanent magnetic grip- per for energy-efficient handling of ferromagnetic workpieces	
Integrated	Integrated			
External	External	External	External	
ECM	ECM	ECG	ECG	
 Optimum standard solution for many fields of application Flexible use due to controllable gripping force, position, and speed 	 Optimum standard solution for many areas of application; flexible use due to controllable gripping force, position, and speed 	Universally applicable, compact gripper, with large diversity of parts	Universally applicable, compact gripper, with large diversity of parts	
•	•	•	•	
•	•	•	•	
•	0	•	•	
•	0			
0	0	0	0	
	9	ű	-	

Patented Precision!
Patentierte Präzision!
Multi-tooth guidance

SCHUNK Grippers

Electric

The new SCHUNK Gripper PGN-plus-E

The first electric gripper with reliable multi-tooth guidance. Multi-tooth guidance, digital actuation and 24 V drive with permanent lubrication.

The new electric SCHUNK PGN-plus-E gripper transfers the proven high performance features of the new PGN-plus-P pneumatic gripper directly to the area of mechatronic handling. The first electric gripper with proven multi-tooth guidance with permanent lubrication, digital actuation, and 24 V drive makes the changeover from pneumatic to electric components particularly easy. Its actuation via digital I/O simplifies commissioning, enabling rapid integration in existing systems.

Your benefits:

- NEW: Up to 50% longer gripper fingers due to higher maximum moments
- Four-stage gripping force for simple adaptation to sensitive workpieces
- NEW: Lifelong maintenance-free
 The SCHUNK multi-tooth guide with continuous lubrication pockets ensures even lubrication.
- NEW: 24 V drive and actuation via either digital I/O or IO-Link Class B connection for a simplified commissioning and fast integration into existing systems
- · Integrated sensor system





schunk.com/pgn-plus-e



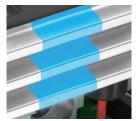
Up to 50% longer gripper fingers

The improved multi-tooth guidance enables the use of even longer gripper fingers for the same gripper size due to higher maximum moments, without overloading the guidance.



Gripping force adjustable to four stages

The gripping force of the new SCHUNK gripper PGN-plus-E can be quickly, safely and manually adjusted in four stages.



Maximum life span due to lubrication pockets in the robust multi-tooth guidance

Permanent lubrication pockets ensure a continuous grease supply. At the same time, it ensures that an even lubricant film is created rapidly, even with short strokes.



Maximum process safety

The multi-tooth guidance enables a greater diagonal pull surface, and therefore a lower surface pressure, for process-reliable and low-wear transmission of power to the base jaw.



Integrated sensor system

The control and power electronics are already completely integrated so that no space is taken up in the control cabinet. The 24 V gripper is actuated via digital I/O inputs. Up to 2 gripper positions can be queried via one M8 connection.

	Universal Gripper with Shank Interface GSW-B	Universal Gripper with Shank Inter- face and Compensation Unit GSW-B with AGE	Vacuum Gripper with Shank Interface GSW–V
Comprehensive ranges	++	++	+
Variety of sensor systems	+	+	
Description	Universal gripper with shank interface for toolholder	Universal gripper with shank interface for toolholder and compensation unit	
Field of application			
	For fully automated loading and unloading of machining centers	 For fully automated loading and unloading of clamping devices such as vises 	For fully automated loading and unloading of flat workpieces
ambient conditions			
Clean	•	•	•
Contaminated/coarse dust	•	0	0
Contaminated/fine dust and liquids	0	0	0
Contaminated/aggressive liquids	0	0	
High temperature range > 90 °C	•	•	
Cleanroom	0	0	

= very highly suitable

- = highly suitable
- O = suitable in customized version
- + = medium-sized selection ++ = wide selection +++ = wide large selection

SCHUNK PZN-plus with Shank Interface GSW-B

The SCHUNK GWS gripper with shank interface loads and unloads machining centers fully automatically using the machine's own axis. It is inserted in a toolholder like a tool and can be swapped lightning fast out of the tool rack, and loaded from the tool changer into the machine spindle directly by the machine without requiring a robot or gantry.

The result: fully automatic workpiece change only with the help of the machine axis. Operation via the coolant supply.

- · 30% higher productivity due to automated machine loading
- · No additional energy supply required in the machine



Magnetic Gripper with Shank Interface GSW-M	Cleaning Device with Shank Interface RGG	LOG	O-Ring Gripper ORG
+	+	+++	+
Magnetic gripper with shank interface for toolholder	Cleaning device with shank interface for toolholder	Lightweight gripper made from a chemical resistant polyamide with a closed membrane system.	6-finger gripper reliable internal and external assembly of 0-rings
 For fully automated loading and unloading of ferromagnetic work- pieces 	 For cleaning of clamping devices and for automating cleaning of machine tools 	 Particularly suitable for highly dynamic applications with light workpieces For handling of small parts and plastic parts, as well as sand core handling 	• For automated assembly of 0-rings
•	•	•	•
0	•	•	
0		•	
	•		
		0	0

SCHUNK ORG Special Gripper for O-ring Assembly

The SCHUNK 0-ring gripper must be positioned with custom fingers can be used to mount, 0-rings and other sealing rings, both on shafts (external assembly) and in bores (internal assembly).

Your benefits:

• **Up to 30% time saving** as the external and internal assembly can be done with one gripper



	Gripping Hands	
	Intelligent	
	Servo-electric 5-Finger Gripping Hand SVH	Servo-electric 3-Finger Gripping Hand SDH
	First DGUV certified 5-finger hand	2014
Technical data		
Overall length [mm]	242.5	248.8
Total width [mm]	92	120.2
Max. finger width [mm]	19.6	46.4
Finger length [mm]	102.7	155
Finger spacing [mm]	25	66
Ratio to human hand	1:1	1.4:1
Number of drives	9	7
Number of fingers	5	3
Degrees of freedom	20	7
Weight [kg]	1.3	1.95
IP class	20	50
Power supply [V DC]	24	24
Nominal current [A]	0.16	2
Max. current [A]	3.5	5
CAN		•
RS232		•
RS485	•	
Ethernet TCP/IP		•
Environment		
Clean environment	•	•
Easily contaminated environments		•
Tactile sensor systems		
Tactile sensor systems		•

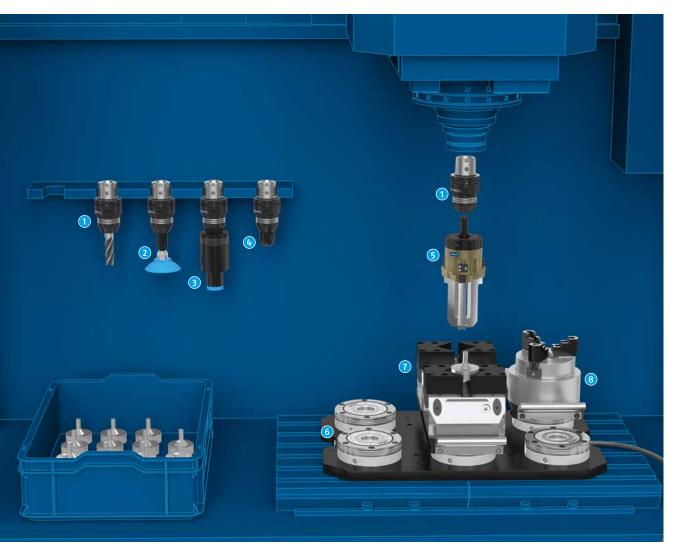
Special Grippers

Lean Automation

SCHUNK Lean Automation:

Gripping Systems and Clamping Technology for the Automation of your Machine Tool

When it comes to precision, when seconds are decisive, set-up times are too long and costs too high, there is no room for compromise. And this is precisely where SCHUNK's lean automation range comes in. Because your machine can do more than you think. With efficient and suitable solutions for loading, changing, and cleaning. And of course with optimum tool and workpiece clamping.



- TENDO E compact Hydraulic Expansion Toolholder The ultimate tool for every cutting tool, for every application
- Vacuum Gripper GSW-V for handling workpieces with a flat surface
- Magnetic Gripper GSW-M for handling ferromagnetic workpieces
- Cleaning Unit RGG for cleaning the machine room in a matter of seconds
- SCHUNK Universal Gripper PZN-plus with shank interface

for automatic loading and unloading of your tooling machine

- **TANDEM Clamping Force Blocks**for workpiece clamping in confined spaces
- 8 ROTA Lathe Chuck for precise clamping of round workpieces

Handling and Assembly – SCHUNK has the perfect Solution for every Requirement.

With our wide range of pneumatically and electrically driven linear, rotary and gripper standard components and many products for robots, SCHUNK offers perfect prerequisites for individual handling solutions. An enormous variety of automated solutions can be implemented by using just a few standard components – fast, simple, and professional.

Application-specific automation systems provide high dynamics during short cycle times – from small parts assembly in the production of electronics to the loading and unloading of machine tools to the handling of food products, pharmaceuticals or medical devices.





Over 4,000 standard components in the most comprehensive selection of modules for handling and assembly

















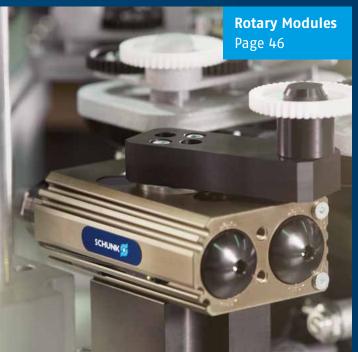












New! Linear Module ELP

Easily adjustable in a Maximum of 60 Seconds.

In a Class of its Own!



NEW: Electric Holding Brake

For protection against falling mounting loads in vertical applications in the case of a loss of energy.

Handling

Product Overview

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Rotary Modules

Pneumatic

Technical data Angle of rotation < 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Angle of rotation > 360 ° [°] 90 180 90/180 Weight [kg] 0.09 0.71 0.65 8.3 90.27 90.2				
Technical data Angle of rotation < 360 ° [°] Angle of rotation > 360 ° [°] Angle of rotation > 360 ° [°] Number of sizes 3	Rotary Modules, pneumatic	Vane Swivel Unit		
Technical data Angle of rotation < 360 ° [°] Angle of rotation > 360 ° [°] Angle of rotation > 360 ° [°] Number of sizes 3		SFL	RM-W	
Angle of rotation < 360 ° [°] Angle of rotation > 360 ° [°] Number of sizes 3 Torque [Nm] 0.1 3.6 0.7 22 Weight [kg] 0.09 0.71 0.65 8.3 Max. permissible mass moment of inertia [kgm²] Repeat accuracy [°] Protection class IP Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotary actuator with a high torque for easy rotation tasks Wivel vane with high torque for fast rotation tasks Single your fast rotation tasks Field of application The optimum solution for easy rotation tasks For fast movement cycles		COMPAND OF THE PROPERTY OF THE		
Angle of rotation > 360 ° [*] Number of sizes 3				
Number of sizes Torque [Nm] O.13.6 O.722 Weight [kg] O.090.71 O.558.3 Max. permissible mass moment of inertial [kgm²] Repeat accuracy [°] Protection class IP Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed—through Electric rotary feed—through Electric rotary feed—through Electric rotary feed—through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application - The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty - For fast movement cycles	Angle of rotation < 360 ° [°]	90 180	90/180	
Torque [Nm] 0.13.6 0.722 Weight [kg] 0.090.71 0.658.3 Max. permissible mass moment of inertia [kgm²] 0.05 up to 0.036 Protection class IP 52 40 Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application Ambient conditions Clean Slightly dirty • • •	Angle of rotation > 360 ° [°]			
Weight [kg] Max. permissible mass moment of inertia [kgm²] Repeat accuracy [°] Protection class IP Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application Ambient conditions Clean Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Center position ATEX-certified Field of application The optimum solution for easy rotation tasks For fast movement cycles	Number of sizes			
Max. permissible mass moment of inertia [kgm²] Repeat accuracy [°] Protection class IP Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application Ambient conditions Clean Ambient conditions Clean Slightly dirty 0.005 up to 0.036 Swivel vane with high torque for fast rotation tasks Swivel vane with high torque for fast rotation tasks	Torque [Nm]			
of inertia [kgm²] Repeat accuracy [°] Protection class IP 52 Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/lopening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application Ambient conditions Clean Ambient conditions Clean Slightly dirty 52 40 Swivel vane with high torque for fast rotation tasks bevieve for easy rotation tasks Swivel vane with high torque for fest rotation tasks	<u> </u>			
Protection class IP Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty Swivel vane with high torque for fast rotation tasks Swivel vane with high torque for fast rotation tasks	· · · · · · · · · · · · · · · · · · ·	0.005	0.27	
Description Rotary actuator with a high torque for easy rotation tasks up to 180° Gripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application - The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty - Swivel vane with high torque for east rotation tasks Swivel vane with high torque for east rotation tasks Swivel vane with high torque for east rotation tasks Swivel vane with high torque for east rotation tasks	Repeat accuracy [°]	0.05	up to 0.036	
high torque for easy rotation tasks fripping force [N] Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • torque for fast rotation tasks torque for fast rotation tasks	Protection class IP	52	40	
Stroke per jaw [mm] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean • • • • • • • • • • • • • • • • • • •	Description	high torque for easy rota-	torque for fast rotation	
Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty Max. permissible [kg] Closing/opening tells [mm] Ambient conditions Clean Slightly dirty	Gripping force [N]			
Closing/opening time [s] Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks • For fast movement cycles Ambient conditions Clean • • •	Stroke per jaw [mm]			
Max. permissible finger length [mm] Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Recommended workpiece weight [kg]			
Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Closing/opening time [s]			
Center bore Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty For fast movement cycles	Max. permissible finger length [mm]			
Pneumatic rotary feed-through Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty For fast movement cycles	Options/versions			
Electric rotary feed-through Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Center bore			
Center position ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Pneumatic rotary feed-through			
ATEX-certified Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Electric rotary feed-through			
Gripping force maintenance device Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • • • • • • • • • • • • • • • • • • •	Center position			
Rotation adapter Monitoring options Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • Sightly dirty	ATEX-certified			
Monitoring options Inductive proximity switches Magnetic switches Field of application The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty Monitoring options For fast movement cycles	Gripping force maintenance device			
Inductive proximity switches Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • Sightly dirty				
Magnetic switches Field of application • The optimum solution for easy rotation tasks Ambient conditions Clean Slightly dirty • The optimum solution easy rotation tasks • For fast movement cycles	• •			
Field of application • The optimum solution for easy rotation tasks • For fast movement cycles • Slightly dirty	· ·		•	
The optimum solution for easy rotation tasks - For fast movement cycles	_	•		
Ambient conditions Clean Slightly dirty for easy rotation tasks	Field of application			
Clean • • Slightly dirty • •			For fast movement cycles	
Clean • • Slightly dirty • •	Ambient conditions			
Slightly dirty		•	•	
	Slightly dirty	•	•	
	Extremely dirty			

^{• =} fully supported

<u> </u>			
Rotary Actuators			Swivel Heads
SRU-mini	RM-F	SRU-plus	SRH-plus

0180	0190	0180	180
0 100	0 150	0 100	160
4	6	8	7
0.16 1.15	0.05 1.9	3 115	369.9
0.15 0.65	0.046 1.6	1.2 26.5	2.1 21.2
0.01	0.023	32	2.6
0.07	up to 0.082	0.05	0.05
65	40	67	67
Light and fast flat swivel unit with multiple options such as fluid feed-through, hydraulic damping, hydraulic-elastomer damp- ing and a pneumatic center position	Light and fast rotary unit	Universal unit for pneumatic swivel and turning movements	Universal swivel head SRH- plus for fast loading and unloading tasks, with inte- grated fluid and electrical feed-through
•	•	•	•
•		•	•
		•	•
•	•	•	
		•	•
• For fast movement cycles	• For fast movement cycles	For universal use with any swiveling movement	Recommended for loading and unloading machine tools
•	•	•	•
•	•	•	•
		•	•

	Rotary Finger	Rotary Indexing Tables	Rotary Gripping Modu Parallel Gripper	les with 2-Finger
SKE	GFS	RST-D	GSM-P	RP
00	00 100		0 100	0 100
90	90 180	22.5 90	0180	0190
4	4	3	4	5
0.4 9	0.64 10	3.1 29.3	0.3 2.9	0.38 1.9
0.4 9	0.55 5	1 8.3	0.3 2.9	0.5 2.2
0.15 1.95	0.55 5	0.6	0.57 1.51	0.5 2.2
		0.0		
0.03	0.07	up to 0.04	0.02	0.02
30	54	50	30	40
90° swivel head with single piston drive	Rotary finger for turning work- pieces that are held by a gripper or can also be used as a special rotary unit	Ring indexing unit for endlessly turning with a rotation angle up to 90° per cycle.	Compact gripper swivel combination, consisting of a powerful rotor drive and a 2-finger parallel gripper	Compact 2-finger parallel gripper swivel module with double piston rack and pinion swivel drive
			39 162	50 420
			1.5 10	2.5 8
			0.2 0.61	0.25 1.4
			0.01 0.05/ 0.01 0.05	0.015 0.06/ 0.015 0.06
			64	100
		•		
				•
			•	•
				•
For light exter- nal loads	• For universal use	• For fast move- ment cycles	For gripping and swiveling small to medium-sized workpieces in clean environments	For gripping and swiveling work- pieces in clean environments
•	•	•	•	•
	•	•		•

Rotary Modules

Pneumatic

SCHUNK Universal Rotary Actuator SRU-plus

Robust. Quick. Powerful.

Universal pneumatic unit for rotary and turning movements in both clean and dirty areas.



schunk.com/sru-plus

- Graduated series with uniform torque increase
 the correct size is available for delivery for many applications.
- Selectable angle of rotation either 90° or 180°, complete freedom in choice of angle of rotation; special angles available on request
- Choice of end position adjustability: +3°/-3° (small) or +3°/-90° (large)
- Choice of pneumatic or locked center position; locked center positions can be unlocked under load. The two types of center position always allow further rotation in either direction.
- Fluid feed-through suitable for gases, liquids, and vacuum
 no need for troublesome hoses
- Electrical rotary feed-through for continuous fail-safe feed-through of sensor and actuator signals; bus feed through available on request
- Choice of electronic magnetic switches or inductive proximity switches
 - for absolute variability in position sensing
- Series extends downwards
 with SRU mini-series for a broad range of applications

Adaptable Intelligent
Technical data
Technical data Number of sizes 1 3 Torque [Nm] 75 4,3 98 Max. speed [min-1] 62.5 13 78 Weight [kg] 15.5 1.9 6.4 Max. permissible mass moment of inertia [kgm-1] Repeat accuracy [*] 0.035 0.93 Gear ratio 48 51 161 Intermediate circuit/nominal voltage [v] Nominal current [A] 5 12 Diameter of center bore 22 Number of electric feed-throughs 0 0 0 Number of pneumatic feed-throughs 8 0 0 Number of pneumatic feed-throughs 8 0 0 Number of pneumatic feed-throughs 8 0 0 Street on class IP 65 40 Type of measuring system Angle of rotation > 506°, center bore and optional feed-throughs Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[*] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable Integrated Controller External Integrated Controller External Integrated Controller type Motor-dependent Prevenuatic rotary feed-through Electric rotary feed-through
Number of sizes 1 3 3 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 75 75 75 75 75 75 7
Number of sizes 1 3 3 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 75 75 75 75 75 75 7
Number of sizes 1 3 3 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 4.3 98 75 75 75 75 75 75 75 7
Torque [Nm] 75 4.3 98 Max. speed [min-1] 62.5 13 78 Weight [kg] 15.5 1.9 6.4 Max. permissible mass moment of inertia [kgm²] 20 9.5 Gear ratio 48 51 161 Intermediate circuit/nominal voltage [V] Motor-dependent 24 Nominal current [A] 5 12 Diameter of center bore 22 Number of electric feed-throughs 0 0 0 Number of pneumatic feed-throughs 8 0 Protection class IP 65 40 Type of measuring system Motor-dependent Incremental Angle of rotation Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs precision gear and integrated electronics Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Motor Adaptable External Integrated Integrated Controller type Motor-dependent Integrated Integrated Integrated Integrated Integrated Controller type Motor-dependent Integrated Integrated Integrated Integrated Controller type Motor-dependent Integrated Integrated Integrated Integrated Controller type Motor-dependent Integrated Integrated Integrated Controller type Motor-dependent Pneumatic rotary feed-through Electric rotary feed-through
Max. sped [min-1] 62.5 13 78 Weight [kg] 15.5 1.9 6.4 Max. permissible mass moment of inertia [kgm²] 20 9.5 Inertia [kgm²] 0.035 0.03 Gear ratio 48 51 161 Intermediate circuit/nominal voltage [V] Motor-dependent 24 Nominal current [A] 5 12 Diameter of center bore 22 Number of electric feed-throughs 8 0 Number of pneumatic feed-throughs 8 0 Protection class IP 65 40 Type of measuring system Motor-dependent Incremental Angle of rotation Bescription Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Motor Adaptable Stromal Integrated Integrated Integrated Controller External Integrated Integrated Integrated Controller External Integrated Integrated Integrated Integrated Integrated Controller type Motor-dependent Pneumatic rotary feed-through ● Integrated Integrat
Weight [kg] 15.5 1.9 6.4 Max. permissible mass moment of inertia [kgm²] 20 9.5 Repeat accuracy [⁰] 0.035 0.03 Gear ratio 48 51 161 Intermediate circuit/nominal voltage [V] Nominal current [A] 24 Diameter of center bore 22 Number of electric feed-throughs 0 0 0 Number of pneumatic feed-throughs 8 0 0 Protection class IP 65 40 Type of measuring system Motor-dependent Incremental Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[⁰] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Motor Adaptable Integrated Integrated Integrated Controller External Integrated Controller Stevensor Motor-dependent Motor-dependent Motor-dependent Diameter Stevensor Motor-dependent Integrated Integrated Integrated Controller type Motor-dependent Motor-dependent Motor-dependent Diameter Stevensor Motor-dependent Motor-dependent Motor-dependent Diameter Stevensor Motor-dependent Motor-dependent Motor-dependent Diameter Stevensor Motor-dependent Motor-dependent Diameter Stevensor Diameter Stevensor Diameter Stevensor Diameter Stevensor Diameter Diam
Max. permissible mass moment of inertia [kgm²] Repeat accuracy [°] Gear ratio Haw Motor-dependent Description Electric rotary module with adaptable servomotor, angle of rotation Bescommended workpiece weight [kg] Closing/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor Adaptable Adaptable External Integrated Integ
Inertia [kgm²] Repeat accuracy [°] Gear ratio 48 51161 Intermediate circuit/nominal voltage [V] Nominal current [A] Diameter of center bore Number of electric feed-throughs Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Controller Controller (Controller) Options/versions Center bore Pneumatic rotary feed-through ■ 0.0 0 0 0 0 0 0 0 0 0 0 0 0
Repeat accuracy [°] Gear ratio 48 51 161 Intermediate circuit/nominal voltage [V] Nominal current [A] Diameter of center bore 22 Number of electric feed-throughs Nomber of pneumatic feed-throughs Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor Controller Controller Controller Controller Controller bye Options/versions Center bore Pneumatic rotary feed-through Motor Ged-through Electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Integrated Integrated Integrated Integrated Integrated Integrated Find Type and Type a
Gear ratio 48 51 161 Intermediate circuit/nominal voltage [V] Motor-dependent 24 Nominal current [A] 5 12 Diameter of center bore 22 Number of electric feed-throughs 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Intermediate circuit/nominal voltage [V] Nominal current [A] Diameter of center bore 22 Number of electric feed-throughs Protection class IP Type of measuring system Angle of rotation Description Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Controller Controller (Spread) Options/versions Center bore Pneumatic rotary feed-through Motor (Agaptable) Plectric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary actuator with angle of rotation > 360°, precision gear and integrated electronics Servo-electric rotary feed frough Servo-electric rotary feed frough Motor-dependent Description Servo-electric rotary feed frough
Nominal current [A] Diameter of center bore 22 Number of electric feed-throughs Number of pneumatic feed-throughs Protection class IP 65 40 Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Integrated Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through 5 12 5 12 5 12 5 12 5 12 5 12 5 12 5 12 6 10 Adoptable Integrated
Diameter of center bore Number of electric feed-throughs Number of pneumatic feed-throughs Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Controller External Controller type Options/versions Center bore Pneumatic rotary feed-through 0 0 0 0 0 0 0 0 0 0 0 0 0
Number of electric feed-throughs Number of pneumatic feed-throughs Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Controller type Motor-dependent Motor-dependent Pneumatic rotary feed-through Electric rotary feed-through
Number of pneumatic feed-throughs Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Controller Controller type Motor Adaptable External Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Biochamber Adoption Motor Ged-through Electric rotary feed-through Electric rotary feed-through Electric rotary feed-through
Protection class IP Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller Controller Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Motor feed-through Electric rotary feed-through Electric rotary feed-through Incremental Adoptable with angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics Integrated Integrated Integrated Integrated Integrated Electric rotary feed-through Electric rotary feed-through
Type of measuring system Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Motor (Stroke/opening angle [Nm]) Motor (Stroke/opening angle per jaw [mm]/[°]) Electric rotary feed-through Electric rotary feed-through
Angle of rotation Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary module with adaptable with angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics Integrated
Description Electric rotary module with adaptable servomotor, angle of rotation > 360°, center bore and optional feed-throughs Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Options/versions Center bore Pneumatic rotary actuator with angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics With angle of rotation > 360°, precision gear and integrated electronics
adaptable servomotor, angle of rotation > 360°, precision gear and integrated electronics Gripping force [N]/opening angle [Nm] Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics with angle of rotation > 360°, precision gear and integrated electronics
Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Stroke/opening angle per jaw [mm]/[°] Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Recommended workpiece weight [kg] Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Controller External Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Closing/opening time [s] Max. permissible finger length [mm] Motor & Controller* Motor Adaptable Integrated Controller External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Max. permissible finger length [mm] Motor & Controller* Motor Adaptable Integrated Controller External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Motor & Controller* Adaptable Integrated Controller External Integrated Controller type Motor-dependent Options/versions • Center bore • Pneumatic rotary feed-through • Electric rotary feed-through •
Motor Adaptable Integrated Controller External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Controller External Integrated Controller type Motor-dependent Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Controller type Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Options/versions Center bore Pneumatic rotary feed-through Electric rotary feed-through
Center bore Pneumatic rotary feed-through Electric rotary feed-through
Pneumatic rotary feed-through Electric rotary feed-through
Electric rotary feed-through
Didne -
Field of application
Universal, extremely flexible rotary module Suitable for use as a component in a handling or positioning system Suitable for use as a component in a handling or positioning system As an axis for lightweight arms in industrial or service robotics
Ambient conditions
AIIIDIEIIL COITUITUOTIS
Clean • •

⁼ fully supported* = Control concepts for mechatronic SCHUNK components see page 17

^{** =} More controllers available upo

			Drives
PRH	ERD	ERS	PDU 2
3	3	3	3
0.75 6.8	0.4 1.2	2.5 - 10	4.3 98
35 117	600	140 2300	13 78
0.75 1.55	1.2 - 1.8	2.7 - 10.9	1.9 6.1
0.3	0.0012	0.6	
0.004	0.01	up to 0.01	0.03
30 100		•	51 161
24	560	48/560	24
1.3 6.5	0.43 1.6	1.2 6.3	5 13
0	4	8	0
0	2	1	0
54 65	40 - 54	40	40
Incremental	Absolute (Hiperface)	Incremental	Incremental
Servo-electric miniature rotary actuator with angle of rotation > 360°, center bore and precision gear	Powerful torque motor with absolute-value transducer and electric and pneumatic rotary feed-throughs	Electric rotary actuator with torque motor and angle of rotation > 360° in optional protection class IP54 plus optional rotary feed-through and holding brake	Servo-electric drive with angle of rotation > 360°, precision gear and integrated electronics
Integrated	Integrated	Integrated	Integrated
Integrated	External Possb Povroth® SIEMENS®**	External Passh Powroth® CLEMENC®**	Integrated
	BoschRexroth®, SIEMENS®**	BoschRexroth®, SIEMENS®**	
		•	
•			
			•
Universal-use, extremely flexible rotary actuator	 For all applications with unusual requirements in terms of repeat accuracy, speed of rotation, accel- eration and service life 	 Universal-use, extremely flexible rotary actuator For applications with unusual requirements in terms of maximum mass moment of inertia, compactness, and reliability As a component in a handling or positioning system 	 Servo drive for linear, rotary or CNC axes Axis motor for measuring and testing technology applications
•	•	•	•
•			•
•			

	2-Axis modules	Gripper Swivel Modules with 2–Finger Parallel Gripper
		Adaptable
PSM 2	PW	EGS
3	2	2
0.16 0.88	12 23/2 12	0.040.11
2125 6500	12 23/2 12	0.040.11
1.3 3.9	1.8/3.4	0.45 1.2
		0.00018
0.2	up to 0.03	1
	121 161/101 121	
24	24	24
6 12		1.6
0	0	
0	0	
40	40	30
Incremental	Incremental	
		30 270
Servo-electric drive with angle of rotation > 360° and integrated electronics	Servo-electric rotary pan-tilt actuator with precision gear and integrated electronics	Compact electrical 2-finger parallel rotary gripper module with smooth-running roller bearing guide
		15 140
		36
		00.55
		0.03 0.22
		50
Integrated	Integrated	Integrated
Integrated	Integrated	Integrated
•		
 Servo drive for linear, rotary or CNC axes Axis motor for measuring and testing technology applications 	 Universal-use, highly versatile rotary pan-tilt actuator As a component in a handling or positioning system for cameras or 	 For electrical gripping and swiv- eling of small to medium-sized workpieces up to 270°
	laser scanners • Can be used as a wrist module on robots	
_		
•	•	•

Rotary Modules

Electric

SCHUNK Gripper Swivel Unit EGS

The world's most compact electric gripper swivel unit.

The SCHUNK electric gripper swivel unit EGS facilitates the switch to pneumatic-free handling solutions. For the first time ever, it successfully combines electrical gripping and swiveling in the smallest space in a compact housing. The low-maintenance and price-attractive module paves the way for highly efficient pneumatic-free systems. Coupling of the gripping and rotation gear, patented by SCHUNK, allows continuous rotation without an electric feed-through.



Your benefits:

- Quick switch to pneumatic-free handling
- Simple, fast commissioning without external regulators and additional programming
- Gripping and swiveling with this extremely compact module
- Swiveling time 0.18 s/180°
- Gripping time 0.03 s/stroke
- Freely definable angle of rotation between 30° and 270°
- 4 digital inputs (open gripper, close gripper, turn left, turn right)
- Controlled with 24 V

schunk.com/gripper-swivel-module-egs

SCHUNK Rotary Module ERS with Rotary Feed-through DDF

Compact, dynamic and uniquely versatile

The electric SCHUNK rotary module ERS offers the option of a pneumatic or electric rotary feed-through. This module is driven by a torque motor with a hollow shaft and features a rotary feed-through, making it one of the most compact electric rotary modules with an integrated pneumatic and electric feed-through on the market. As standard, the rotary feed-through has more than eight signal feed-throughs and a pneumatic air duct.



Your benefits:

- Extremely flat design
- Dynamically stable and torsion-proof
- With pneumatic and electric feed-through
- Endlessly turning at up to 250 RPM
- Simple systems integration due to standard sensor interface
- Great process versatility due to free choice of intermediate positions
- High acceleration and short cycle times due to high torque

schunk.com/ers-with-ddf

Pneumatic Linear Modules	Stroke Module	Compact Slide	Universal Linear Module LM	
Drive type				
Piston rod cylinders	•	•	•	
Rodless cylinder				
Technical data				
Number of sizes	4	6	5	
Number of pistons	1	1	1	
Repeat accuracy [mm]	up to 0.01	up to 0.01	up to 0.01	
Useful stroke [mm]	0150	0150	0 450	
Max. driving force [N]	482	482	753	
Weight [kg]	0.5 5.64	0.07 5.32	0.44 15.81	
Adjustable end positions	Yes	Yes	Yes	
Max. end positions adjustment per side [mm]	25	25	25	
Guidance type	Cross roller guide	Cross roller guide	Cross roller guide	
Comprehensive ranges	+	++	+++	
Required maintenance	Hydraulic shock absorbers, lubrication of the guide, replacement of seals	Hydraulic shock absorbers, lubrication of the guide, replacement of seals	Hydraulic shock absorbers, lubrication of the guide, replacement of seals	
Note	Optionally available with rod lock	Optionally available with rod lock	Optionally available with up to two intermediate positions and with rod lock	
Field of application				
	Compact Optimum for lifting workpieces Ideal for space-opti- mized applications	 Universally applicable Optimum for short- stroke applications For demanding requirements with respect to precision 	Universally applicable For demanding requirements with respect to precision, flexibility and rigidity	
Ambient conditions				
Clean	•	•	•	
Slightly dirty				
Dirty				

^{● =} fully supported ○ = technically possible + = medium-sized selection ++ = wide selection +++ = very wide selection

Linear Modules

Pneumatic

Linear Module KLM	Gantry Axis PMP
•	
	•
4	2
1	1
up to 0.02	0.04
0300	03700
753	250
0.5 13.2	3 44.91
Yes	Yes
25	50
Ball bushing guide	(Double) profiled rail guide
++	+++
Hydraulic shock absorbers, lubrication of the guide, replacement of seals	Hydraulic shock absorbers lubrication of the guide, replacement of seals
Optionally available with up to two intermediate positions, rod lock and dustproof version	Optionally available with bellow, several interme- diate positions and cable track
Simple stroke module Optimum use as Z-axle in handling modules For high requirements of flexibility	Robust and precise gantry systems For large range of stroke
•	•
•	•
0	

SCHUNK Universal Linear Module LM

Pneumatic linear modules LM from SCHUNK are characterized by long life span and reliability. The use of cross roller guides convinces with respect to accuracy, rigidity, and low friction. And also in terms of minimal space requirements, the linear modules score with their very compact design, even when two guide rails running in parallel are used.



Your benefits:

- 5 sizes with a total of 52 stroke variants
- · High availability off the shelf
- Over 20 years of experience with cross roller guides
- · Can be flexibly combined by up to 38 fastening threads on one side
- · No additional interfering contour when adding shock absorbers or sensors

Intermediate Stops ZZA for Pneumatic Linear Modules LM and KLM

Up to two intermediate stops ZZA are possible per linear module. Therefore up to four positions are available to the linear unit. With the intermediate stops ZZA on a linear unit, NOK parts (not OK parts) can be rejected for instance on an assembly station.



- Up to two intermediate positions possible
- No oscillations in the intermediate position
- · Can be moved from the intermediate position in both directions

SCHUNK Linear Module ELP

The new benchmark for mechatronic linear modules.

The SCHUNK ELP is the most easy to adjust electric linear module on the market and is put into operation more quickly than the pneumatic linear module. Due to the revolutionary auto-learn function, no more shock absorbers are required. This makes the SCHUNK ELP practically wear-free and therefore robust and long-lasting. Actuation can be done in decentralized manner using a fieldbus distributor or directly over digital signals.





schunk.com/linear-module-elp

- Simple 1:1 replacement of pneumatic through mechatronic components
- No shock absorbers, therefore no wearing parts and maintenance-free!
- Commissioning in just 2 working steps due to the revolutionary auto-learn function
- Simple speed configuration using two rotary switches
- 0.01 mm repeat accuracy due to low-play roller guidance
- Linear direct drive for high dynamics and long lifespan

	Electric Linear Modules			
	Alternative	Intelligent		
	Compact Linear Module ELP	Compact Linear Module	Compact Linear Module ELB	
		ELM	CLB	
		H		
Drive type				
Spindle drive				
Toothed belt drive				
Rack and pinion drive				
Direct drive (linear motor)	•	•	•	
Technical data				
Number of sizes	3	2	1	
Repeat accuracy [mm]	±0.01	±0.05	±0.01	
Max. useful stroke [mm]	200	260	125	
Max. driving force [N]	104	160	150	
Max. speed [m/s]	Auto-learn function	1.5	4	
Max. acceleration [m/s ²]	Auto-learn function	40	100	
Type of measuring system		Hall-effect sensor	Absolute or incremental	
Guidance type	Cross roller guide	Profiled rail guide	Cross roller guide	
Comprehensive ranges	++	++	+++	
Required maintenance	Maintenance-free	Cleaning of the magnetic tracks, lubrication of the guide	Cleaning of the magnetic tracks, lubrication of the guide	
Note	Axis with mechanically adjustable stop positions, optionally available with load balance	Freely programmable, optionally available with rod lock	Freely programmable, optionally available with rod lock, brake or load balance	
Motor & controller				
Motor	Integrated	Integrated	Integrated	
Drive controller	Integrated	LinMot®	BoschRexroth®, SIEMENS®*	
interfaces	Digtal I/O	Sercos III, EtherNet/IP, EtherCAT, PROFINET, PROFIBUS DP, PowerLink, CANopen	Sercos III, EtherNet/IP, EtherCAT, PROFINET, PROFIBUS DP, PowerLink, CANopen	
Field of application				
	Simple, compact short stroke module For small loads For exceptionally dynamic positionings	Extremely compact and simple short stroke module For small loads For exceptionally dynamic positionings	Compact and simple short stroke module For small loads For exceptionally dynamic positionings	
Ambient conditions				
Clean	•	•	•	
Slightly dirty				

^{• =} fully supported

^{+ =} medium-sized selection ++ = wide selection +++ = extremely wide selection

* = Additional controllers available upon request ** = Depending on the drive type

Short Stroke Module LDH	Stroke Module LDK	Universal Linear Module LDN	Universal Linear Module LDM
•	•	•	•
	2		
1	2	2	2 ±0.01
±0.01 200	±0.01 400	±0.01 2700	2700
125	500	500	1000
4	4	4	4
40	40	40	40
Absolute or incremental	Absolute or incremental	Absolute or incremental	Absolute or incremental
Steel rail guide	Roller guide	Roller guide	Roller guide
+	++	+++	++
Cleaning the magnetic tracks	Cleaning the magnetic tracks	Cleaning the magnetic tracks	Cleaning the magnetic tracks
Freely programmable, option- ally available with brake, limit switch, reference switch, cable track, supported profile	Freely programmable, option- ally available with brake, limit switch, reference switch, cable track, supported profile	Freely programmable, option- ally available with brake, limit switch, reference switch, cable track, supported profile	Freely programmable, optionally available with brake, limit switch, reference switch, cable track, supported profile
Integrated	Integrated	Integrated	Integrated
BoschRexroth®, SIEMENS®*	BoschRexroth®, SIEMENS®*	BoschRexroth®, SIEMENS®*	BoschRexroth®*
Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS	Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS	Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS	Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS
Compact and simple short stroke module For small loads For extremely dynamic movements in the Z axis	Compact and simple short stroke module For small loads For exceptionally dynamic positionings	Universally applicable Linear motor axis with simple X-profile For applications with demanding requirements with respect to dynamics For a faster and precise movement or controlled press-in operation of workpieces in the high-speed assembly	Universally applicable Linear motor axis with double X-profile For medium loads with very high dynamic and precise requirements For a faster and precise movement or controlled press-in operation of work-pieces in the high-speed assembly
•	•	•	•
Ţ.	· ·	ū	

		Adaptable	
Universal Linear Module	Flat Linear Module	Compact Linear Module	Linear Table
LDT	LDL	ELS	Alpha
		•	•
_			
•	•		
2	2	2	1.
2	2	2	4
±0.01 2700	±0.01 3800	±0.01 260	±0.03 2540
1500	500	150	18000
4			
	40	1	2.5
40		8.5	20
Absolute or incremental	Absolute or incremental	Motor-dependent	Motor-dependent
Roller guide	Roller guide	Profiled rail guide	Double-profiled rail guide
++ Classics +hs	+	+	++
Cleaning the magnetic tracks	Cleaning the magnetic tracks	Lubrication of the guide and the spindle	Lubrication of the guide and the spindle
Freely programmable, option- ally available with brake, limit switch, reference switch, cable track, supported profile	Freely programmable, option- ally available with brake, limit switch, reference switch, cable track	Freely programmable, also available standard-equipped with BoschRexroth® motor	Freely programmable, option- ally available with customized motor, limit switch and refer- ence switch
Integrated	Integrated	Adaptable	Adaptable
BoschRexroth®, SIEMENS®*	BoschRexroth®, SIEMENS®*	Motor-dependent	Motor-dependent
Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS	Multi-Ethernet (Sercos III, PROFINET IO, EtherNet/IP, EtherCAT), PROFIBUS	Controller-dependent	Controller-dependent
Universally usable linear motor axis with triple X-profile For heavy loads with very high dynamic and precise requirements For a faster and precise movement or controlled press-in operation of workpieces in the high-speed assembly.	Flat linear motor axis For applications with very high dynamic and precise requirements For a faster and precise movement or controlled press-in operation of workpieces in the high-speed assembly.	Compact spindle cantilever axis For short strokes For high precision and driving force requirements	Particularly flat design for table assembly For high precision and driving force requirements
•	•	•	•
			•

Universal Linear Module Beta	Flat Linear Module Delta	Universal Linear Module Gamma
beta	Deita	damma
Night -	4 = = =	
	4 -	
•	•	
•		•
Ť		
12	5	3
0.03 or 0.08***	up to ±0.03**	up to ±0.05
7720	7700	7685
18000**	12000**	4000
8	5	5
60	60	60
Motor-dependent	Motor-dependent	Motor-dependent
Double-profiled rail guide	Double-profiled rail guide	Double-profiled rail guide
+++	+++	+++
Lubrication of the guide and (if neces-	Lubrication of the guide and (if neces-	Lubrication of the guide and (if neces-
sary) the spindle, replacement of the	sary) the spindle, replacement of the	sary) the gear rack
cover tape	cover tape	
Freely programmable, optionally available with customized motor, limit	Freely programmable, optionally available with customized motor, limit	Freely programmable, optionally available with customized motor, limit
switch and reference switch	switch and reference switch	switch and reference switch
Adaptable	Adaptable	Adaptable
Motor-dependent	Motor-dependent	Motor-dependent
Controller-dependent	Controller-dependent	Controller-dependent
 Universally applicable 	• Flat design for large loads	• With closed profile for high rigidity
Ball-screw drive for high precision and driving force requirements.	· Universally applicable	requirements
and driving force requirementsBelt drive for high dynamic require-	 Spindle drive for high precision requirements with high driving force 	 With rack and pinion drive for precise applications and large strokes
ments with large stroke	Belt drive for high dynamic require-	Toothed belt drive for dynamic
	ments with large stroke	applications
•	•	•
•	•	•

Linear Modules

Electric

SCHUNK Linear Module Beta

Linear module with adaptive drive.

The product range includes 12 sizes. Depending on the application, choose between spindles, belt or rack and pinion depending on the drive type as well as between roller guidance and profile rail guidance. The Beta series is outstanding for its economical axis applications with high requirements with respect to dynamism and smooth running. Even long stroke lengths can be implemented with this drive system.

Your benefits:

- 12 profile sizes
 - 3 drive types (spindle/belts/gear rack)
- · 2 guide systems
- 100% modular for high availability
- 20 years of experience with linear systems
- 100% flexible actuation due to adaptable motors



schunk.com/beta

Accessories for spindle, belt and rack and pinion driven Linear Modules

Servomotors

With the **linear modules Alpha, Beta, Gamma, Delta** and **ELS** with **adaptable**drive, you receive from SCHUNK on request
an already completed configuration with
servomotors that is designed in accordance
with your specific application and technical
requirements. We can use servomotors either
from BoschRexroth®, SIEMENS® or SCHUNK.

We will be happy to supply you with the required IndraDrive series controller from BoschRexroth® or the SINAMICS series from SIEMENS® – depending on the servo motors used. Naturally, you have the option of attaching any other servo motor yourself to the linear axes listed.



BoschRexroth® Servo motor



SIEMENS® Servo motor



Compact SCHUNK servo drive type PDU 2 with precision gears and integrated controller

Pneumatic and electric

	Lifting/Rotary Unit	Pick & Place Unit	
	Pneumatic	Pneumatic	Electric*
	DRL	PPU-P	PPU-E
Technical data			
Number of sizes	2	2	3
Horizontal stroke in Y [mm]		121 210	0 280
Horizontal stroke in X [mm]			
Vertical stroke [mm]	23 40	30 45	0150
Rotating angle [°]	90 180		
Useful load [kg]	03	03	05
Repeat accuracy X-axis [mm]			
Repeat accuracy Y-axis [mm]		up to ±0.01	±0.01
Repeat accuracy Z-axis [mm]	±0.01	up to ±0.01	±0.01
Repeat accuracy, rotary [°]	0.02		
Weight [kg]	2.7 5	4.5 15.5	15 35
Max. cycle time/picks per minute	63	95	110
Actuation	Pneumatic valve	Pneumatic valve	External controller
Protection class IP	40	40	40
Guidance type	Guidance/ deep groove ball bearing	Cross roller guide	Profiled rail guide
Number of possible combinations			
Comprehensive ranges	+	+	++
Motor & controller*			
Motor			Integrated
Drive controller			BoschRexroth®, SIEMENS®*
Options/versions			
Rod lock	•	•	•
Center position	•		
Integrated valve			•
Additional C-axis			•
Drive package			
Description	Compact lifting/rotary unit consisting of a powerful short-stroke cylinder and a rack and pinion swivel actuator	Compact 2-axis unit for running a typical pick & place motion	Compact 2-axis unit for flexible running of any curve on one plane
Field of application	 For the rapid and precise transfer and turning of workpieces in high-speed 	 For the rapid and precise transfer of workpieces in high-speed assembly 	 For the rapid and precise transfer or controlled press- in operation of workpieces in high-speed assembly
	assembly		in high speed assembly
Ambient conditions	assembly		in high speed assembly
Ambient conditions Clean	assembly •	•	•

^{• =} fully supported + = medium-sized selection ++ = wide selection * = Control concepts for mechatronic SCHUNK components see page 17 ** = More controllers available upon request

Standard Gantries				
Pneumatic	Electric*	Electric*		
Line Gantry LPP	Line Gan	try LPE	Room Gantry RPE	
1	2	00	2	
200 1500	500 15	00	500 1500	
0 225	100 50	0	500 1500 100 500	
0 225	100 50	U	100 500	
05	020		0 20	
05	0 20		±0.08	
±0.01	±0.08		±0.08	
±0.01	±0.08		±0.03	
±0.01	±0.03		±0.03	
Pneumatic valve	Controlle 40	on external motor	Controller on external motor	
Profiled rail/ cross roller guide	Profiled r	ail guide	Profiled rail guide	
234	90		150	
+	+		+	
	Adaptabl	е	Adaptable	
BoschRexroth®, SIEMENS®*	BoschRex	roth®, SIEMENS®*	BoschRexroth®, SIEMENS®**	
•				
•				
		•	•	
Line gantry with a horizont gantry axis, and a vertical, linear module		ry with a horizontal, electric pelt axis, and a vertical, electric xis	Room gantry with two electric toothed belt axes in a horizontal direction, and one electric spindle axis in a vertical direction	
 For easily conducting the two-dimensional handlin bly tasks for small to med workpieces 	ig and assem- two-dir	ly conducting the most common nensional handling and assem- s for medium-sized and large ces	 For easily conducting the most common three-dimensional handling and assem- bly tasks for medium-sized and large workpieces 	
•		•	•	
		•	•	

Change Systems	Quick-change Systems			
	sws	SWS-L	EWS	GWS
Product features				
Manual actuation				
Pneumatic actuation	•	•		•
Electric actuation			•	
Locking monitoring possible	•	•	•	•
Tool presence monitoring possible*	•	•	•	
Pneumatic energy transmission	•	•	•	•
Electric energy transmission	•	•	•	•
Technical data				
Number of sizes	14	4	1	3
Recommended workpiece weight [kg]	0 - 450	01350	18	0170
Moment load M _{xy} [Nm]	3 9870	7600 13500	56.5	225 1200
Moment load M _z [Nm]	3.5 8460	4060 16200	78	300 1800
Repeat accuracy [mm]	up to 0.01	0.01	±0.015	0.04
Weight [kg]	0.25 19.1	7.8 28	1.8	0.85 4
Screwed flange on the robot	Adapter plates/ direct assembly ISO-9409	Adapter plates/ Direct mounting ISO-9409	Adapter plates	Adapter plates Direct mounting ISO-9409
Advantages/your added value				
	 Patented self-sust tem for a reliable the quick-change quick-change ada Standardized stora available for any s 	connection between head and the pter ge modules	Integrated locking queries Control via digital I/O for easy commissioning and rapid integration into existing systems	Integrated pneumatic feed—throughs for reliable electric—ity, gas and water supply of the tools Robust wedge—hook kinematics for a secure connection be—tween the gripper change head and the gripper change adapter
Ambient conditions				
Clean	•	•	•	•
Slightly dirty	•	•	•	•
High-temperature and stainless steel version on request	•	•		

^{*} Tool presence monitoring optionally available with SWS-076, SWS-110, SWS-160 and SWS-300. SWS-L and EWS included in the scope of delivery.



SCHUNK Quick-change System SWS

Fast effector change for high flexibility in production, handling and assembly.

When changing grippers, tools and other end-effectors, an automatic quick-change system (as robot accessory) can clearly reduce manual work or even entirely replace it. While manually re-equipping a pneumatic effector takes ten to thirty minutes, a quick-change system reduces this time down to ten to thirty seconds, with merely locking and unlocking taking even just milliseconds.

	Manual Change Systems		
NSR-A	SHS	CWS	MWS
	•	•	•
•			
•	•		
•	•		
•	•	•	•
•	•		•
2	6	5	2
	058	028	01
75 600	15 320	20 160	0.5 1
200 1600	25 775	10 200	0.2 0.75
0.02	0.02	0.01	0.1
0.41.6	0.14 4	0.07 0.445	0.007 0.016
Adapter plates ISO-9409	Adapter plates/ direct mounting ISO-9409	Adapter plates	Adapter plates
 Form-fitting lock, self-locking, for a reliable connection be- tween the pallet change head and the pallet change adapter Integrated piston stroke moni- toring and tool presence control for monitoring the system 	 Integrated pneumatic feed-through for secure energy supply of the handling modules and tools Optionally available with monitoring of the locking and presence monitoring 	 Flat and weight-optimized through direct assembly of the gripper onto the change sys- tem without adapter plate. Integrated pneumatic feed- throughs for reliable electricity, gas and water supply of the grippers 	Extremely flat design for minimal interference contours Integrated feed-throughs for six pneumatic or electrical signals
•	•	•	•
•	•		
•			

- · Payloads up to 1,350 kg possible
- Patented self-locking locking system
- No-Touch-locking™
 Secure locking without making contact, for the SWS even when the SWK and SWA do not touch
- 21 sizes for optimal size selection and a broad application range
- All functional components made of hardened steel for high bearing load capacity of the change system
- Transmission possibility for electric, pneumatic and fluid media
- For a process-reliable connection between the quick-change head and the quick-change adapter with self-sealing couplings

	Compensation Uni	ts		
	AGE-XY	AGE-Z 2	AGE-S	AGE-W
	$x \leftrightarrow y$	CRANKS Z	$x \leftrightarrow y \xrightarrow{\uparrow} z$	R R
Product features		_	· ,	
Pneumatic locking				
Position memory		•		
Screwed flange acc. to ISO-9409 standard				
Monitoring via proximity switch Technical data			•	
	2	2	,	4
Number of sizes	3	3	4	1
Compensation stroke XY [mm]	±2.5 ±4	2 40	412	
Compensation stroke Z	10 16	8 10	10 14	
Rotatory compensation [°]	±12 ±16			±19
Spring force [N]		20 120	240 1100	
Piston force Z at 6 bar in extended position [N]		500 1500	800 3000	
Piston force Z at 6 bar in retracted position [N]		300 1450		
Weight [kg]	0.46 1.5	0.55 1.7	2.6 29.5	2.7
Locking force at 6 bar [N]	235 580		800 2700	
Horizontal payload [kg]	0 10	05	0100	23
Vertical payload [kg]	0 15	0 12	0160	
Repeat accuracy [mm]	0.01	0.02	0.1	±0.09
Axial force F _z [N]	1700 3200	200 500	110 2000	
Moment load capacity M _x , M _y [Nm]	16 30	10 - 30	30 500	68
Twist torque M _z [Nm]	3.5 9	20 - 80	30 250	62
Angular compensation x [°]				±13
Angular compensation y [°]				±13
Angular compensation z [°]				±13
Advantages/your added value				
	Robust guid- ance for high moment loads even with minimal space requirements.	 Locking in order to switch the unit rigid in retracted or ex- tended position. 	 Three compensation directions XYZ in one unit. Compact design for minimal design heights. 	 Deflection in rotation and in the angle compensates for inaccuracies in the component position. Centric locking via ball system. Protective cover is optionally available.
ISO flange pattern, simple assembly on most types of robot without additional adapter plates	•	•	•	
Field of application				
	Universally applica workpieces with hi	ible for assembling, palle igh precision	tizing and inserting	For use in assembly, for loading and unloading and for bin picking
Ambient conditions				
Clean	•	•	•	•
Slightly dirty			•	•
High-temperature version on request	•	•	•	

less s	Tolerance Compensation U	
AGE-F	TCU	FUS
$x \longleftrightarrow y$	es R ✓	$x \leftrightarrow y \Leftrightarrow R$
	•	•
•	•	•
4	8	5
±1.5 ±5		±1.7 ±2.2
		0.4 1.3
	11.5	2.5 5
0.5 190		
0.1 3.1	0.08 2.45	0.05 to 1.8
0.1 3.1	30 700	0.03 to 1.0
0 32	30 100	
0.01	up to 0.02	up to 0.01
75 1600		9 395
3.5 50	355	1.1 45.2
6 150	1.0 32	
	1 - 2	1
	1	1
	1.2 2	
 Spring reset and spring force adjustable in three spring stiffnesses. Defined centric position with a high repeat accuracy. Compensation stroke flexibly adjustable. 	 Pneumatic locking. Long-lasting elastomers, rigid unit during travel. 	Compensates for angular errors and tolerances with jointing applications. This reduces the cycle times and increase the productivity. The pneumatic locking ensures that the unit can be locked centrically and rigid again.
Direct assembly of paral- lel and centric grippers. SCHUNK grippers PGN-plus, PZN-plus can be mounted onto AGE-F without addi- tional adapter plate.	Direct mounting of parallel and centric grippers, no additional adapter plate required.	
Assembling, palletizing and	In the fields of assembly	Assembly tasks with very little
inserting workpieces without feeding external media.	automation and machine tool loading.	play among the parts to be aligned.
•	•	•
	•	•

SCHUNK Compensation Unit AGE-S-XYZ

Palletizing, joining and assembling with flexibility.

The compensation unit AGE-S extends the AGE series (AGE-XY/AGE-Z/AGE-F) for the medium and heavy load range. The compensation unit provides the required flexibility between the effector and the robot arm.

The AGE-S-XYZ helps you to avoid damage to the system and malfunctions, while increasing process reliability. During handling in XY- as well as Z-direction, the unit can be made rigid using the integrated pneumatic lock and eccentrically locked using the position memory in XY-direction.



- The housing consists of highstrength, hard-coated aluminum alloy
- The functional components are made of **hardened steel**
- Three compensation directions in one unit, compact design for minimal heights
- Centric locking for rigid switching of the unit at a defined centric position
- Pneumatic position memory for eccentric locking in deflected position

Rotary Feed-throughs	Rotary Feed-throughs DDF 2	Stationary Rotary Feed-through DDF-SE
Product features		
Endless rotary movement	•	•
Screwed flange acc. to ISO-9409 standard	•	
Pneumatic energy transmission	•	•
Vacuum energy transmission		
Electric energy transmission	•	•
Bus transmission		
Technical data		
Number of sizes	12	2
Recommended workpiece weight [kg]	0 250	
Max. speed [RPM]	120	500
Continuous torque [Nm]	0.8 22	413
Starting torque [after shutdown] [Nm]	1.3 25	6 20
Forces F _z [N]	1000 9000	2000 4000
Moments M _x , M _y [Nm]	15 to 550	60 250
Moments M _z [Nm]	10 400	60 250
Pneumatic energy transmissions	2 4	4 6
Electrical energy transmission	410	68
Weight [kg]	0.5 14.2	3.3 9
Advantages/your added value		
	Three versions to choose from Version 1: For the feed-through of pneumatic and electrical signals. Version 2: For the feed-through of pneumatics. Version 3: For the feed-through of electrical signals.	Standardized shaft end for easy assembly of gears. Revolutions of up to 500 RPM Your gripping system is safely supplied with pneumatics and electronics even in the event of fast, endless rotary movements of up to 500 RPM.
Combined pneumatic and electric feed-through	•	•
ISO flange pattern, simple assembly on most robot types without additional adapter plates	•	
Field of application		
	Rotary feed-through for reliable pneumatic and electric feed-through in the event of robot applications with endlessly rotating movements.	Ideally suitable for the use on rotary indexing tables and for stationary applications.
Ambient conditions		
Clean	•	•
Slightly dirty	•	•

W 1 6	6.1.5.15.15	
Measuring Systems	6-Axis Force/Torque Sensors FTN	FTD
		E O E O E
Protection class IP	NET	DAQ
Without IP protection		
IP60		
IP65		•
Technical data	•	•
	16	16
Number of sizes	16	16
Calibration	SI-12-0,12 SI-40000-6000	SI-12-0,12 SI-40000-6000
Evaluation electronics	Net-Box	DAQ card
Weight of sensor [kg]	0.09 47	0.09 47
Range of measurement F _x F _y [N]	±12±40000	±12 ±40000
Range of measurement F _z [N]	±17±88000	±17 ±88000
Range of measurement M _x M _y [Nm]	±12±6000	±12±6000
Range of measurement M _z [Nm]	±12±6000	±12±6000
Resolution F _x F _y [N]	1/320 1000/160	1/320 1000/160
Resolution F _z [N]	1/320 1000/60	1/320 1000/60
Resolution M _x M _y [Nm]	1/64000 3/2	1/64000 3/2
Resolution M ₂ [Nm] Advantages/your added value	1/64000 3/4	1/64000 3/4
	FTN sensor Evaluation via Ethernet, EtherCAT, DeviceNet, optional PROFINET	FTD sensor Evaluation via DAQ card (PCI, USB)
Sizes with different ranges of measurement	16	16
High measured-value resolution and fast data transmission for nearly real-time control	•	•
Robust version, high overload range for a long life span	•	•
Rotation and translation of the coordinate systems in all three directions in space	•	•
Easy operation, minimized commissioning time	•	•
Field of application		
	Universally usable in robot applications such as hap research and development.	otics, medicine, grinding, inspecting, joining and
Ambient conditions (sensor)		
Clean	•	•
Slightly dirty	•	•
Extremely dirty	•	•
Humid	•	•

Wireless Transmitter FTS Stand-Alone 16 SI-12-0,12 .. SI-40000-6000 Stand-Alone-Controller 0.09 .. 47 ±12 .. ±40000 ±17 .. ±88000 ±12..±6000 ±12 .. ±6000 1/160 .. 1000/80 1/160 .. 1000/30 1/32 .. 3/1 1/32 .. 3/2 • Handy wireless transmitters for the Evaluation via analog voltage 6-axis force/torque sensors SCHUNK (0-10 V or DIO) FT-Nano and SCHUNK FT-Mini · WiFi transmission allows easy integration of up to 6 sensors into existing WiFi · Wireless transmission for mobile applications 16 Universally usable with robot applications such as haptics, medicine, grinding, inspecting, joining and research and development.

SCHUNK 6-Axis Force/Torque Sensor FTN

Interface variety with Ethernet, EtherNet/IP, EtherCAT, DeviceNet and a CAN interface.

With its high-speed data output, four possible communication protocols, remote monitoring via LAN and configuration via web interface, the 6-axis force/torque sensor FTN is currently the most multi-functional force/torque sensor for industrial automation. Suitable for machining tasks in the field of e.g. grinding and polishing, robot assemblies or robotic surgery as well as applications in rehabilitation and neurological applications. The sensor allows for automating difficult assembly, machining and finish machining tasks, that could previously only be performed by hand or using complex special machines.



- · 16 sizes
- Torque ranges between 0.12 Nm and 6,000 Nm
- Load ranges between 12 N and 40,000 N
- The sensor measures the force and torque in all six degrees of freedom.
- Simple process integration due to simple interface compatibility
- Possible remote monitoring, via LAN connection

Rotary Feed-through

Robot Accessories

SCHUNK Rotary Feed-through DDF 2

More powerful. More versatile. More energy efficient.

The DDF 2 is the latest standard for state-of-the-art robot and assembly applications. It ensures highest process reliability even with 360° unlimited rotational movements. SCHUNK offers the DDF 2 in three variations: for the feed-through of pneumatics or

electrical signals or for the combined version. A significantly increased load allows the use of a steel shaft for transmitting dynamic forces and moments. Due to a specially developed seal, the DDF 2 ensures a long service life and energy efficiency due to the possibility of using smaller drives.



- 85% longer service life due to newly developed seals
- 50% greater moment load due to transmission of the dynamic forces and moments via a steel shaft
- · 20% greater load capacity
- Newly developed, smoothly running and especially durable seals produce a smaller starting and continuous torque, which allows you to use smaller, i.e. more economical drives
- Depending on the size, two and four pneumatic feed-throughs are standard, as are between four and ten electrical transmissions for signals 1 A/60 V
- Allows for 360° continuous rotation
- Complete series with 14 sizes for optimal size selection
- Electrical connector contacts enable rapid and easy replacement in the event of cable breakage at the robot arm or gripper

	Collision and Overload Sensors	
	OPS	OPR
	Manual reset	Automatic reset
Product features		
Pneumatic actuation	•	•
Built-in spring optionally available		•
Technical data		
Number of sizes	4	7
Moments M _x , M _y [Nm]	7.5 430	6 2000
Forces F _z [N]	500 7000	440 14000
Axial deflection [mm]	9.5 12	5.1 16
Angle deflection [°]	4 12	813
Rotatory deflection [°]	45 360	20
Repeat accuracy [mm]	up to 0.02	±0.025
Operating pressure range [bar]	0.5 6.0	1.4 6.2
Weight [kg]	0.4 7.0	0.24 11.7
Advantages/your added value		
Automatic return position for faster resuming of production after a collision		•
Integrated monitoring for signal transmission in the event of a collision	•	•
Triggering force and moment can be set via the operating pressure for optimum protection of robot and components	•	•
ISO adapter plates are optional for simple assembly on most types of robot without additional production costs	•	•
Field of application		
Standard solution for all robot applications where robots, tools, or workpieces are to be monitored for possible collisions	•	•
Ambient conditions		
Clean	•	•
Slightly dirty		•
Humid		•

SCHUNK OPR, Collision and Overload Sensor

The effective protection both for robots and for handling devices against damage as a result of collision or overload.

Unique with automatic return position.

The SCHUNK collision and overload sensors OPR effectively monitor the robot as well as handling devices. SCHUNK OPR features an automatic return position, enabling the system to resume production as soon as possible after a collision. In case of overloads or collisions, the tool plate deflects and, at the same time, automatically actuates the system's emergency stop. The system's sensitivity can be adjusted via the operating pressure.



- Automatic reset into the center position
- Overload detection occurs in X-, Y- (+/-) and Z-direction and equally during rotation around the X-, Y- and Z-direction
- Integrated cable breakage control to avoid malfunctions
- Also available as **IP65** protected version
- Triggering forces and moments can be adjusted via operating pressure

Machining Tools

Robot Accessories

x \(\daggreup\)	Axial 2 250 ±4.1	Axial 1 390 ±7.515
ial 1040 1 ±9.1	Axial 2 250 ±4.1	1 390
ial 1040 1 ±9.1	Axial 2 250 ±4.1	1 390
ial 1040 1 ±9.1	Axial 2 250 ±4.1	1 390
) 1040 1 ±9.1	2 250 ±4.1	1 390
) 1040 1 ±9.1	2 250 ±4.1	1 390
1 ±9.1	250 ±4.1	390
1 ±9.1	±4.1	
		±7.5 15
5 ±5.1		
	±2	±7.5
89	1 25	1474
4.1	13	0.34 4.1
000 25000	30000	5600
7.6	6.6	9
19		
6		9.5
4.53	0.51	3.3
•	•	
		•
•	•	•
•	•	
•	•	•
	4.1 0025000 7.6 19 6 4.53	4.1 1 3 00 25000 30000 7.6 6.6 19

SCHUNK Deburring Spindle FDB

The solution for perfect finishing.

Clean Extremely dirty

SCHUNK standard solution for flexible and robot-guided deburring of all sorts of workpieces. The drive of the unit is carried out via a pneumatic spindle with of up to 65,000 RPM – depending on the unit size. For compensating part tolerances during machining, the shank has compliant bearings.

Your benefits:

- Flexible high-frequency spindle for maximum versatility for deburring
- Adjustable rigidity of the deburing spindle by means of the pneumatics
- For clean chamfer edges in every installation position
- High rotational speeds
- For **high** feed rates
- Versatile use on the robot arm or applicable as a stationary unit

The right Solution for every Application

SCHUNK original accessories for sensor systems and pillar assembly components enhance the versatility and the field of application of our standard modules for your application. Optimum functionality, reliability, and precise positioning are ensured by SCHUNK original accessories. Experience highest quality and utmost longevity.

Original accessories for an excellent accuracy of fit and function. Compatible for every SCHUNK standard product, easy integration into existing plants and systems.





Pillar assembly system 100% variable, thousands of combinations of SCHUNK components are possible

The world's **most extensive** range of accessories for gripping systems

More than 150 sensors for precise force measurement and workpiece and position monitoring



Pillar Assembly System | Accessories I Sensor Systems

Product Overview



SCHUNK











Sensor Systems Page 86









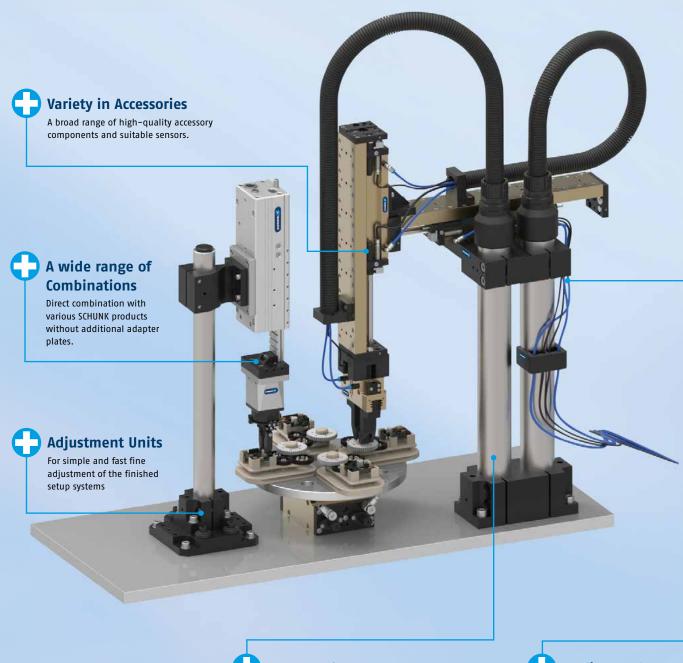




SCHUNK Pillar Assembly System SAS

More than 10,000 combination Possibilities

100% Flexibility for your Applications





100% flexible

Various customized lengths of the pillars possible as standard. Individual or double pillars can be selected.

Various support plates for horizontal, vertical or variable connection on five sides



Media supply

Simple and fast combinations from the modular system

Pillar Assembly System | Accessories I Sensor Systems

Product Overview

Content

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SCHUNK Pillar Assembly System SAS.

With more than 10,000 possible combinations, SCHUNK offers the world's most comprehensive range of pillar assembly applications. The SCHUNK pillar assembly system allows for a combination of diverse handling modules without mechanical adaptation by means of mounting and centering holes, for an exact fit and angular precision as well as the safe, stable, and reproducible mounting of components.

Over 10,000 possible Combinations.



Adjustment Unit VEH For easy fine adjustments of the finished assembly

- For linear and rotary compensation
- Adjustable with hexagon socket wrench
- Suitable for single and double sockets



Pillar Assembly System High level of precision despite high modularity and flexibility

- · 3 different pillar diameters
- Up to 1,000 mm pillar length
- 17 elements combined as desired
- Direct screw connection for SCHUNK components



Media Routing Simple and fast combinations from the modular system

- Precise hose and cable guidance possible
- Either through the hollow pillars or attached with clips along the pillars
- Media hose for supplying the actuators can be mounted directly

Pillar Assembly System

Connecting Elements

	1 Adjustment Unit	2 Pillar Assembly Sys	tem		
	Adjustment Unit	Base Support	Base Support	Hollow Pillars	Horizontal Mounting Plates APEH/APDH
	VEH	SOE	SOD	SLH	Pidles APEN/APUN
Application with					
Pillars Ø 20 mm		•	•	•	•
Pillars Ø 35 mm	•	•	•	•	•
Pillars Ø 55 mm	•	•	•	•	•
Material	Aluminum, hard-anodized	Aluminum, hard-anodized	Aluminum, hard-anodized	Steel, hard-chromium plated	Aluminum, hard-anodized
Description	The adjustment unit simplifies mechan-ical adjustment of complete handling systems	The base support is the base used for the pillar assembly system and can be directly mounted onto a firm surface	The base support is the base used for the pillar assembly system and can be directly mounted onto a firm surface. A 2-pillar assembly can be mounted with the SOD	Versatile steel pillars can be inserted at various lengths and provide high rigidity	The mounting plates connect the various SCHUNK modules of the modular system to the pillar system
Field of appli- cation	For universal use with structures that must be readjusted during assembly.	The base used for all pillar assemblies with a single pillar	The base used for all pillar assemblies with a double pillars	For all assembly systems and frames and as a mounting option for automation components	For attaching SCHUNK linear modules with horizontal movement
Advantages	 Mechanical adjust- ment High degree of flexibility 	Robust and highly precise	Robust and highly precise	Robust and highly precise Weight-optimized due to hollow profile Can be used as a hose and cable channel	 Robust and highly precise Standardized interface for many SCHUNK products

^{• =} highly suitable/fully supported O = suitable to a limited extent

Vertical Mounting Plates APEV/APDV	Horizontal Mounting Plates AMEH/AMDH	Vertical Mounting Plates AMEV/AMDV	Axial Mounting Plates APDA/APEA	Adjustment ring STG/STR
•				0
Aluminum,	Aluminum,	Aluminum,	Aluminum,	Aluminum,
hard-anodized	hard-anodized	hard-anodized	hard-anodized	hard-anodized
The mounting plates connect the various SCHUNK modules of the modular system to the pillar system	The mounting plates with functional screw connection diagram connect various SCHUNK modules or customized structures to the pillar system	diagram connect various	The mounting plates with functional screw connection diagram connect various SCHUNK modules or customized structures to the pillar system	The adjustment ring provides accurate positioning of the assembly elements that are mounted to the pillars
For attaching SCHUNK linear modules with horizontal and vertical movement	For horizontal attachment of customized structures or other automation components	For vertical attachment of customized structures or other automation components	For attaching customized structures or other automation components	For positioning mounting plates of the pillar assembly system
Robust and high-precison Standardized interface for many SCHUNK products	Robust and high-precision Flexible mounting options	Robust and high-precision Flexible mounting options	 Robust and high-precision Flexible mounting options Mounting options on five sides 	 Fine adjustment High degree of flexibility

		3 Media Routing			
Cross Connector	Mounting Plate	Mounting Clip	Hose Routing	Hose Routing	
KVB	MPL	MFC	SPL/MFB/MFS	MFS/MFV/MFK	
				#	
_	_				
•	•				
•	•	•	•	•	
Aluminum, hard-anodized	Aluminum, hard-anodized	РОМ	РОМ	РОМ	
Cross connectors allow for right-angle junctions to be included in the pillar assembly system.	The mounting plate offers the possibility of adding extra functionalities or structures	Mounting clips can be used to mount and route cables and hoses along the pillars	directly attachable to the	The hose routing, which is directly attachable to the pillars, allows for pneumatic hoses routed via the media channels or actuator cables to be routed further from within the hollow pillars	
For expanding the pillar assembly system vertically	For supporting or mounting additional structures	For all pneumatic or electric sensors and actuators that are mounted to the pillar system	For all pneumatic or electric sensors and actuators that are mounted to the pillar system	For all pneumatic or electric sensors and actuators that are mounted to the pillar system	
 Robust and high-precision High degree of flexibility 	 Robust and high-precision High degree of flexibility 	 Module attachable Reduction of cable breakage 	 Module attachable Reduction of cable breakage Visual enhancement 	 Module attachment Reduction of cable breakage Visual enhancement 	

SCHUNK Grippers

Our Response to Flexibility: Variety in Accessories.

Along with the world's most extensive gripper range, SCHUNK also provides an unmatched range of offering. The PGN-plus universal gripper features a large number of variants and a superior range of accessories offering everything needed for flexible use in your specific automation application. For each kind of application and handling requirement – including under extreme conditions. (15) 17 26

	ABR/SBR	BSWS-B/-A	ABR/SBR-BSWS	BSWS-AR/-UR	UZB	SDV-P
	26	32	20 24	2025	18	
Jaw quick- change system		•	•	•		
Adjustable in- termediate jaw					•	
Top jaws blank	•		•			
Pressure main- tenance valve						•
Field of application	For quick and easy creation of top jaws by adding the clamping contour	With highly diverse workpieces for quick jaw changes with any clamping contours	With highly diverse workpieces for quick jaw changes with simple clamp- ing contours	With highly diverse workpieces for quick jaw changes with any clamping contours	With highly diverse workpieces that can be covered by increasing the clamping width	For applications in which the force or position must be maintained temporarily
Description	Finger blanks made of aluminum or steel for appli- cation-specific rework	The BSWS consists of one base and two adapter pins. The form-fit locking mechanics ensures a fast exchange of the gripper fingers	The BSWS consists of two adapter pins and one finger blank with locking mechanism. The form-fit locking mechanics ensures a fast exchange of the gripper fingers	The BSWS consists of two adapter pins and the locking mechanism located in the customized finger. The form-fit locking mechanics ensures a fast exchange of the gripper fingers	Allows fast tool- free and reliable replugging and shifting of top jaws	With a loss of air pressure, venting of the module will be prevented temporarily by the pressure mainte- nance valve
Advantages	Matching finger blanks for commonly used gripper types Clamping contour can be machined rapidly and easily	One gripper can be used universally in various applications Quick and easy for high flexibility Firm up to the max. loadability of the base jaws	One gripper can be used universally in various applications Quick and easy for high flexibility Firm up to the max. loadability of the base jaws Matching finger blanks for commonly used gripper types Clamping contour can be machined rapidly and easily	One gripper can be used universally in various applications Quick and easy for high flexibility Firm up to the max. loadability of the base jaws Clamping contour can be created as required	Toolless adjust- ment and clamp- ing for quick and easy conversion Stable guide bar, suitable for long gripper fingers	Versatile in its application, since it has standard air connections Manual air bleed screw means no removal of pressurized hoses

Benefit from the SCHUNK Modular System with over 4,000 standard Components.

More than 30 years of expertise in gripping forms the basis for the largest standardized range of gripping technology in the world with more than 4,000 components, a modular system with perfectly matching standard components on linear modules, turning and rotary actuators and robot accessories.

SCHUNK Compact Change System CWS

The flat and weight-reduced manual change system CWS from SCHUNK ensures the fast manual change of grippers at the robot when re-equipping for a new range of parts. A noticeable increase in productivity can thus be achieved in particular for small and medium batch sizes.

- · Simple tool change on the robot due to the simple working principle
- · Full compatibility due to integrated ISO robot flange
- The screw connection diagram is used to mount the most important SCHUNK gripping and compensation modules directly on the quick-change system without an adapter plate



SCHUNK presents the TCU, a compensation unit with base plates connected together by elastomer elements. As a result, the TCU can compensate in the X and Y directions, allowing it to correct angle errors and provide rotational compensation.

- · Suitable for gripper types PGN-plus, PZN-plus, DPG-plus and DPZ-plus
- The compensation travel distances in X/Y directions are two to four millimeters depending on the size, while the compensation angles are between 1.5 and 3.5°
- · Maximum handling weights between 1 and 24 kg, depending on gripper size

SCHUNK Universal Rotary Actuator SRU-plus

Universal pneumatic unit for swiveling and turning movements in both clean and dirty areas.

- · Graduated series with a steady increase in torque
- Swivel angle can be selected as either 90° or 180°
- End position adjustability: +3°/-3° (small) or +3°/-90° (large)
- · Middle position can be selected as pneumatic or locked
- Fluid feed-through of gases, fluids and vacuums without bothersome hoses, as
 well as electric rotary feed-through for long-lasting and safe operational feedthrough of sensors and actuator signals. Optionally with bus feed-through.
- Electronic magnetic switches or inductive proximity sensors for absolute variability in position sensing

Linear Module CLM

Compact linear modules with reduced length and high power density in relation to size. The mini-slides are ideal for use in constrained installation spaces – shock absorbers and proximity switches are integrated into the projection surface and do not give rise to any interference contours.

- · 6 sizes with a total of 22 stroke variants
- · 95% available from stock
- More than 20 years of experience with junction roller guides
- 90% of the applications can be implemented in assembly automation
- 0% additional interference contour due to shock absorbers or sensors









Universal Gripper PGN-plus Universal 2-finger parallel gripper with large gripping force and high maximum moments due to multi-tooth guidance

- Inductive Proximity Switch IN ...
 Inductive proximity switch with molded cables and optional axial/lateral cable outlet
- Flexible Positioning Sensor FPS
 Digital measuring system for monitoring up to five different, freely selectable positions
- Analog Positioning Sensor APS-Z80 Inductive measuring system for accurate detection of the gripper jaw position with analog ouput
- S Analog Positioning Sensor APS-M1S
 Mechanical Measuring System for accurate detection of the gripper jaw position with analog output
- 6 Reed Switch RMS
 Round version of the reed switch
- Telectronic Magnetic Switch MMS 22
 Magnetic switch with either axial or lateral cable outlet for position monitoring
- Programmable Magnetic Switch MMS 22-PI1 Magnetic switch with either axial/lateral cable outlet for monitoring a freely programmable position
- Programmable Magnetic Switch MMS 22-PI2 Magnetic switch with axial cable outlet for monitoring two freely programmable positions
- Programmable Magnetic Switch MMS-P Magnetic switch with axial cable outlet for monitoring two freely programmable positions
- (1) Reed Switch RMS-22

 Reed switch for direct assembly in the C-slot
- Compact Change System CWS Manual change system with integrated air feedthrough for simple exchange of the handling components
- Tolerance Compensation Unit TCU
 Tolerance compensation unit for compensation of small tolerances in the plane
- Compensation Unit XY AGE Compensation unit for compensation of large tolerances along the X and Y-axes
- 65 Adapter Plate ASG Adapter plate for combining various automation components in the modular system

Compact Slide CLM Linear module with pneumatic drive and scopefree pre-loaded junction rollers

- Optical Distance Sensor OAS
 Optical distance and presence sensor for detecting the presence of a workpiece as well as its distance
- (B) Universal Intermediate Jaw UZB The universal intermediate jaw allows fast, tool-free, and safe movement of top jaws on the gripper
- Force-measuring Jaws FMS Force-measuring jaws for measuring gripping forces and workpiece weights
- ② Jaw Quick-change System BSWS-AR

 Adapter coupling of the jaw quick-change system for fast, manual change of top jaws
- 21 Jaw Quick-change System BSWS-B Locking mechanism of the jaw quick-change system for fast, manual change of top jaws
- 2 Jaw Quick-change System BSWS-A Adaptor coupling of the jaw quick-change system for adaptation to the customized finger
- Customized Finger
- Finger Blank BSWS-ABR
 Finger blank made of aluminum with the interface of the jaw quick-change system
- Finger Blanks BSWS-SBR Finger blank made of steel with interface of the jaw quick-change system
- Jaw Quick-change System BSWS-UR
 Locking mechanism for integration of the jaw
 quick-change system into customized fingers
- **EXECUTE**Finger Blanks ABR/SBR

 Finger blanks made of steel or aluminum with standardized screw connection diagram
- Intermediate Jaws ZBA
 Intermediate jaws for re-orienting the mounting surface



Sensor System

	Position Monitorin	g				
	MMS 22	MMS-PI 1/2	IN	RMS	FPS	
						ja
Switching behavior						
1 digital point	•	•	•	•		
2 digital point	•	•				
5 digital point					•	
Analog						
Ambient conditions						
Clean	•	•	•	•	•	
Slightly dirty	•	•	•	•	•	
Extremely dirty				•		
Technical data						
Number of sizes	1	1	6	2	6	
Operating principle	Magnetic	Magnetic	Inductive	Reed	Magnetic	
IP protection max.	67	67	67	67	67	
Supply voltage [V DC]	24	24	24	24	24	
Supply current [mA]	< 50	< 50	< 200	< 10	< 10	
PNP version	•	•	•	•	•	
NPN version	•	•	•	•		
LED display	•	•		•		
Measurement switching distance [mm]	Not adjustable	Not adjustable	0.8 2.5	Not adjustable	Not adjustable	
Closer	•	•	•	•	•	
Opener			•			
Connection type						
Number of wires	3/44	3/4	3	3	7	
Cable version	•	•	•		•	
Connection plug M8 version	•	•	•	•		
Connection plug M12 version			•			

= highly suitable/fully supported

• = suitable in special design (on request)

= suitable to a limited extent



Controller ECM. Modular 24/48 V Controller for SCHUNK Modules

Fast and easy commissioning

The modular SCHUNK controller ECM has been developed particularly for electrically driven gripping and rotary modules with an input voltage of 24 V or 48 V. Equipped with standardized plug connections, it can be quickly and easily connected.

Your benefits

- Service interface USB and two rotary encoding switches
- Standardized plug-in technque for communication and cage clamp terminals for power
- DIP switches with first test and commissioning functions
- Clear information on current controller status via 7-segment display and 4 LEDs
- **Toolless connection** of the cables with spring cage terminals and plug connectors
- Maximum interface flexibility due to PROFIBUS, CAN, 4 digital I/Os and PROFINET

schunk.com/controller-unit-ecm

APS-M1	APS-Z80	MMS-A	Workpiece Monitoring OAS
6	6		
			•
•	•	•	•
	•	•	•
		•	
1	1	1	11
Mechanical	Inductive	Magnetic	Visual
67	67	67	67
24	24	24	24
< 150	< 200	< 50	< 180
			•
		•	
Not adjustable	0.5 2	Not adjustable	10 200
			•
3	3	3	3
•	•	•	•
	•	•	
		•	

Inductive Proximity Switch IN

Reliable. Contactless. Easy assembly.

Inductive proximity switches are used to monitor the current status of automation components. SCHUNK supplies them in two versions: IN (sensor with 30 cm cable and cable connector) and INK (sensor with 2 m supply cable and wire strands for connecting).



Your benefits:

- Bracket mounting for easy and fast assembly
- Version with LED display for checking the switching status directly at the sensor
- Version with plug connector for fast and easy extension cable replacement
- Highly flexible PUR cable for a long service life and resistance against many chemicals
- Proximity switch is flush mountable to reduce interfering contours in the application



Force Measuring System FMS

The SCHUNK force measuring system FMS is used for measuring forces acting in the direction of the jaw movements on the base jaw.
The intermediate jaws FMS are screwed on between the gripper base

jaw and the top jaw, which comes in contact with the workpiece. Gripping forces on the top jaw result in a flow of force through the FMS intermediate jaw. Intelligently arranged strain gauges inside the intermediate jaw react to the resulting deformation. The FMS electronics detects the change in the strain gauges and emits an analog signal indicating the force.

Your benefits:

- Simplest handling via a control line that is directly connected to a PLC
- It is easy to measure the gripping force that is actually acting
- Result output via analog voltage value
- Simple linear relationship between output voltage and gripping force
- Simple zero adjustment with button or via control line
- Integrated LC display for visual monitoring
- · Easy assembly
- Dirt and water-tight for applications even under extreme ambient conditions

All inclusive!

SCHUNK customized Gripping Systems. Benefit from our Experience.

SCHUNK has realized more than **12,000** solutions, a figure that speaks for itself.

Permanent and comprehensive project management is an important part of the SCHUNK philosophy.

Our approach is systematic and tailored to your individual project – each step is traceable and documented.

At SCHUNK, our analysis of complex processes and holistic approach to our customers' parts and products allows us to develop effective, customized gripping systems.

Maximum precision is required in order to present automation processes visually – so we use the latest work technology, from 2D and 3D presentations to 3D simulation. Our components and configurations carry the decisive performance potential that can make your process chain more efficient. We make full use of this potential. And you benefit from this.

Advice

Project planning

Engineering

Implementation

Service



This will pay off for you!

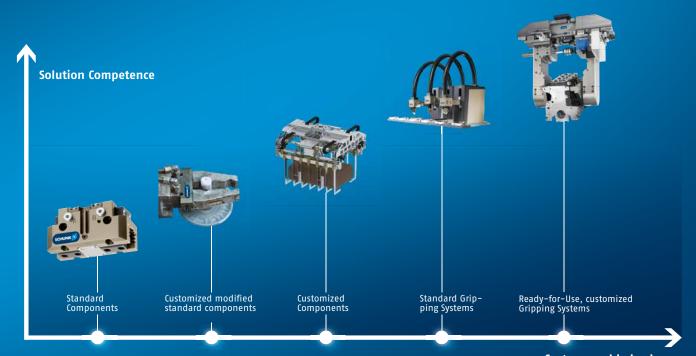
From standard Components to customized Gripping Systems.

personal contact for your solution from one source.

For smooth communications, a personal contact person is available to you from the start of the project until completion. Your contact acts as the liaison between you and those involved in the project, and ensures that information is exchanged smoothly. From planning, to continued support after the conclusion of the project, SCHUNK ensures that your project will be handled cooperatively and efficiently.

Your added value

- Over 30 years of experience with gripping systems
- Over 12,000 implemented gripping systems for most diverse industries
- The world's largest modular system with perfectly adapted standard components
- · Highest accuracy of fit due to standardized interfaces
- · Shorter project lead times due to standardized systems
- Process-reliable implementation and planning security without extra project costs
- · Functional assembly groups fitted on request or ready
- · Time savings due to the perfect solution from a single source



Customer added value

























Handling of Sand Cores

Foundry Industry

Task: Sand cores with different weights and interfering contours need to be gripped in a process-optimized way.

Solution: Using a SCHUNK quick-change system SWS in combination with sealed SCHUNK 2-finger long-stroke grippers PSH ensures a safe and precise hold. The SCHUNK gripping systems are designed for carrying loads up to 200 kg, depending on the application.

Conrod Handling

Automotive Industry

Task: To save costs using multiple handling of conrod parts during production.

Solution: A especially developed conrod gripper based on a SCHUNK pneumatic universal gripper PGN-plus with special gripper fingers is mounted on a SCHUNK rotary module ERM. Due to the rotary module with adaptable drive, this solution can use the same drive as the axis system. This creates a universal drive concept.

Equipped by SCHUNK

Customized Solutions



Handling Plastic Gears

Plastics Industry

Task: Plastic gears must be moved fast and accurately positioned during an assembly process.

Solution: Pneumatic and mechatronic SCHUNK pick & place units from the SCHUNK modular assembly system come individually designed for use. As well as grippers for small components such as the SCHUNK MPG-plus.







Handling of Hinge Parts

Metal Industry

Task: Hinge parts have to be reliably transferred to the workpiece carrier in the linear transfer system.

Solution: Electric and pneumatic SCHUNK pick & place components with pillar assembly system and a compact pick & place unit, SCHUNK gripper for small components EGP and 2-finger parallel gripper PGN-plus as well as an swivel unit SRU-mini come available for use.

Handling of Worm Gear Shafts

Metal-cutting Industry

Task: To remove worm gear shafts in a machining center and store them temporarily before they are machined further.

Solution: A customized SCHUNK gripping system solution comprising two pneumatic 2-finger parallel grippers PGN-plus mounted on a SCHUNK swivel head SRH-plus, which take it in turns to take a ground, finished part from a clamping device and replace it with a blank. Finish-machined parts are deposited on a pallet, raw parts are gripped from the pallet.





SCHUNK Service



Competent and skilled personnel ensure optimal availability of your SCHUNK products, and make sure that their value will be maintained.

Your advantage:

- Fast supply of original spare parts
- Reduction of down-times
- The complete spectrum of components from one source
- Quality and availability that can only be guaranteed by the original manufacturer
- 12-month warranty



Initial operation

- Professional assembly
- · Fast and trouble-free



Inspection

- Inspection is carried out by skilled service engineers
- Avoiding unplanned failures of workholding and toolholding equipment



Maintenance

- Regular maintenance carried out by skilled service engineers
- Increasing and ensuring the availability of your workholding and toolholding equipment



Repairs

- Short down-times due to fast intervention of the SCHUNK service engineers
- Spare parts and accessories

Training

- · Fast and practical training
- Efficient use of your SCHUNK products by training of the operating personnel
- The basis for proper machining of workpieces
- Ensures longevity of your SCHUNK products

Individual service – for better results

- Hotline to our inside technical consultants weekdays from 7 a.m. to 6 p.m.
- Project-oriented and on-site technical advice at your location
- Training on innovations and SCHUNK products across the world in our local subsidiaries

Online service - for a fast overview

All information in digital form, clearly structured and up-to-date on our website at www.schunk.com

- · List of contact persons
- Online product search based on product descriptions
- Product news and trends
- Data sheets
- · Order forms for easy and convenient ordering
- Free download area for pages from our product catalogs and technical data, for software and calculation programs for your gripping and rotary modules
- Free 2D/3D CAD design models, provided in a wide range of different CAD formats – for easy integration into your design!











schunk.com/catalogorder



The SCHUNK Gripper Catalog

The world's most comprehensive gripper portfolio of more than 1,800 pages. Order now!

Catalog order

Copy, complete, fax to **+49-7133-103-2779**

Gripping Systems	Quantity	Clamping Technology	Quantity
Highlights New Products Current innovations in SCHUNK Gripping Systems		Highlights New Products Current innovations in SCHUNK Clamping Technology	
Complete Program Gripping Systems Catalogs SCHUNK Grippers, Rotary Modules, Linear Modules, Robot Accessories		Complete Program Clamping Technology Catalogs Toolholders, Stationary Workholding, Lathe Chucks, Chuck Jaws	
Catalog SCHUNK Grippers The compact SCHUNK Gripping Competence on over 1,760 pages		Catalog Toolholders The complete precision toolholder range for perfect machining on around 520 pages	
Catalog Linear Modules The whole variety of SCHUNK Linear Modules on over 750 pages		Catalog Lathe Chucks Lathe chucks for sophisticated machining of world-renowned quality on 650 compact pages	
Catalog Rotary Modules Cutting-edge technology for rotary movements on more than 610 pages	25	Catalog Chuck Jaws	
Catalog Robot Accessories The SCHUNK End-of-Arm Competence on over 830 pages The optimum interaction between the robot arm and gripper		With 1,200 types – the world's largest chuck jaw program on over 720 pages	
Product Overview SCHUNK Grippers SCHUNK Grippers at a glance		Catalog Stationary Workholding The largest modular system for individualists with more than 500 variants for workpiece clamping on around 830 pages	
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Product Overview Modular Assembly Automation Comprehensive range from the modular system		Catalog Hydraulic Expansion Technology More than 75,000 implemented customized clamping solutions for tool and workpiece	
Product Overview Mechatronics ³ Alternative – Adaptable – Intelligent		Product Catalog TRIBOS Micromachining The No. 1 in Micromachining	
Depanelling Machine			
Product Overview Depanelling Machine		Synergy SCHUNK	
Solutions for the complete spectrum of depanelling technology		Competence Catalog Clamping Technology Gripping Systems The SCHUNK No. 1 service provider for your processing machines and automated production processes	
Company Name		Department	
Street ZIP		City	
Tel. Fax		E-Mail	

No. 1

for safe, precise gripping and holding.



852 minutes without a goal against him in the Champions League

681 minutes without a goal against him on the national team

2 intercepted penalties in the 2006 World Cup

1 headed goal as a goalie

O defeats English Soccer Champion

and

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